

Innovating Energy Technology

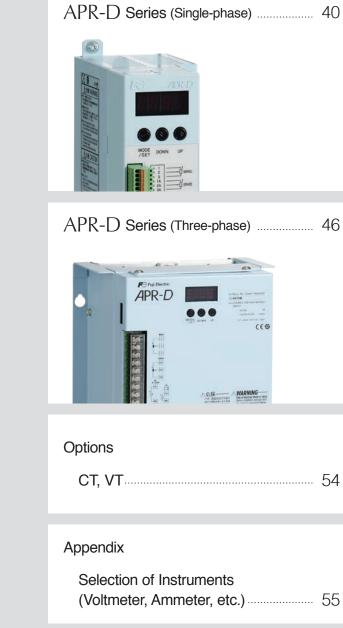
AC Power Regulator



AC Power Regulator

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APR-V Series (single-phase, Three-phase)

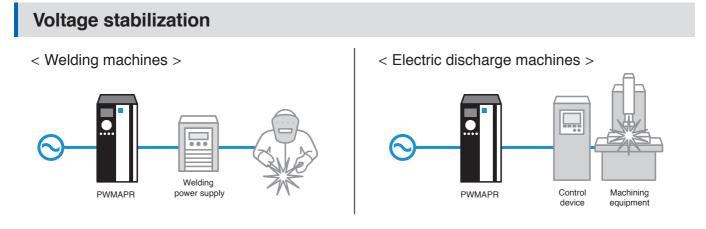


AC Power Regulator for Stabilizing Control – Fuji Electric APR

APR is an abbreviation for AC Power Regulator. An APR is a device that can adjust AC voltage, current, and power steplessly. It is widely used for temperature control of electric furnaces and heaters, as well as for light dimming and AC stabilization power supplies.

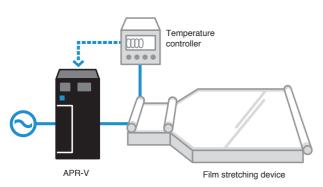
Fuji Electric's APRs use thyristors, IGBTs, and other semiconductors as main devices to stabilize control.

Application examples

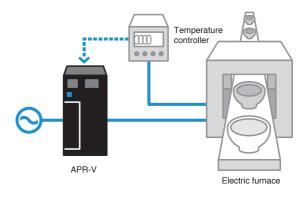


Heat controllers

< Film stretching devices >

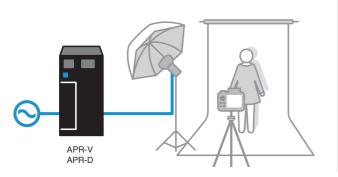


< Electric furnaces >

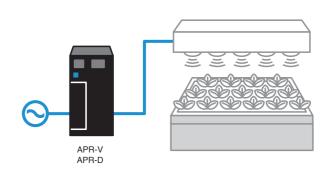


Light dimming

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< Plant factories >



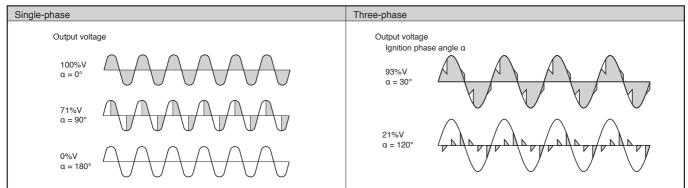


There are three waveform control methods for APRs: a phase control method for switching with thyristors, a cycle control method, and a PWM control method for switching with IGBTs.

Select a waveform control method after understanding the features of each method.

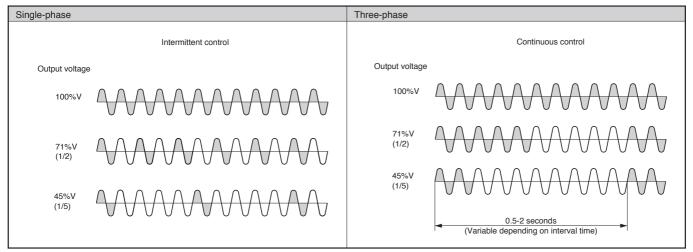
Phase control method (APR-V, APR-D)

The phase control method controls the voltage applied to the load from 0 to 100% by controlling the ignition phase angle α at each half cycle of the power supply frequency.



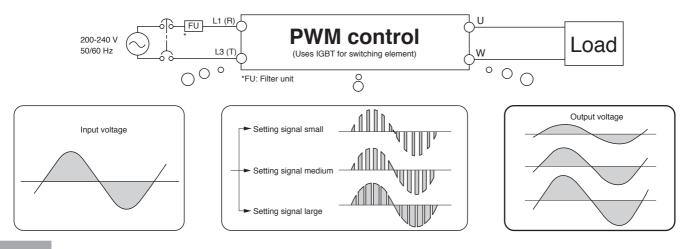
Cycle control method (APR-V, APR-D)

The cycle control method controls the voltage applied to the load from 0 to 100% by controlling the ratio of the on and off periods of one power supply voltage cycle within a fixed period (scanning interval).



■ PWM control method (PWMAPR-M, PWM-APR)

PWM (pulse width modulation) is a control method that applies a new main circuit configuration and high-frequency switching to control the amplitude of the output voltage. As a result, its output voltage waveform is a sine wave and it suppresses harmonic currents.



Features of each control method

The phase control method, cycle control method, and PWM control method have the following features and are used in various ways.

	Dhase control method	Quele control mother d
P WW control method	Phase control method	Cycle control method
Applicable to most loads, such as resistive loads, inductive loads, capacitor loads	Applicable to most loads, such as resistive loads, inductive loads (Capacitor loads are not available)	Applicable to nichrome, ferrochromium- based resistive loads (small temperature coefficient of resistance)
Available	Available	Not available (Available for types with control method P)
Available (comes standard)	Available	Not available
No	Possible occurrence	No
No	No	Possible occurrence
Very fast	Fast	Slow
Very good	Bad	Good
	as resistive loads, inductive loads, capacitor loads Available Available (comes standard) No No Very fast	Applicable to most loads, such as resistive loads, inductive loads, inductive loads, capacitor loads Applicable to most loads, such as resistive loads, inductive loads (Capacitor loads are not available) Available Available Available (comes standard) Available No Possible occurrence No No Very fast Fast

•Circuit classification of harmonic guidelines

- · Phase control method : Circuit classification 7
- · PWM control method : Circuit classification 6 (single phase),
 - 5 (three phase) : Not available
- · Cycle control

	"Conversion factor Ki" of AC power regulator										
Circuit classification		Circuit type	Conversion factor Ki	Major use cases							
5	(Voltage ty	d three-phase bridge pe PWM control) pe PWM control)	K5 = 0	Uninterruptible power system Power supply device for communication Elevator Distributed power supply for grid connection							
6	Self-excited (Voltage ty	d single-phase bridge pe PWM control)	K6 = 0	Power supply device for communication AC electric rolling stock Distributed power supply for grid connection							
	AC power	Resistive load	K71 = 1.6	Reactive power adjusting device							
7	adjusting device	Reactance load (Excluding those for AC arc furnaces)	K72 = 0. 3	Large lighting system Heater							

Feedback control method

Control method	Code	Control method overview			
No feedback function	т	No built-in CT. (No overcurrent detection, heater disconnection detection, etc.) Applied to loads with little resistance change, such as alloy heaters.			
AC CLR	A	CLR = Current limit regulation: Limits output voltage so that output current does not exceed the CLR setting. Applied to applications for limiting the maximum current flowing to the load (e.g., pure metal heaters, etc.).			
AC ACR + AC CLR	В	ACR = Automatic current regulation: Controls the flow of output current in proportion to the set value. Applied pure metal heaters, direct current heating applications, etc. to maintain a constant current.			
AC AVR + AC CLR	С	AVR = Automatic voltage regulation: Controls the output voltage in proportion to the set value. Applied to applications that require output voltage accuracy.			
AC AWR + AC CLR	D	AWR = Automatic wattage regulation: Controls the output power in proportion to the set value. Applied to silicon carbide heaters and sensorless applications that control the heating amount.			
DC feedback control + AC CLR (Feedback input: 0 to10 V DC)	E	Applied when the secondary side of transformers, rectifiers, etc. require accuracy. Controls the feedback value to be 10 V DC when the set value is 100%.			
Transformer primary control via cycle control	Р	Single phase only. Can be applied to insulation transformers and resistive loads (resistance change 20% or less). If the load is 30% or less of the APR rated capacity, output will stop due to a load error.			

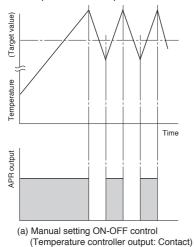
*The PWMAPR-M series supports B, C, and D as standard (switchable using the main unit setting). PWM-APR supports C only. D series single phase products support only T, A, and B, and three phase products support only T. Mini and a series are not supported. For details, refer to " Eeedback control method (PWMAPR-M, PWM-APR, APR-V)" on page 6 and the items in each series.

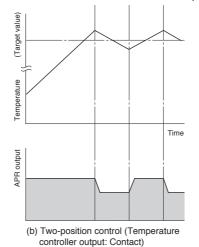
Gradient setter

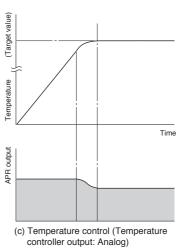
A gradient setter is used to arbitrarily set the magnitude of the output with respect to the set signal. For example, if a 4 to 20 mA DC setting signal is input, the APR output voltage will be at its maximum value at 20 mA, but a gradient setter can be used to change the APR output voltage as desired. When controlling electric furnaces and other heaters, a gradient setter can play an important role as follows.

- (1) Reduces the rated power of the heater and extends the life of the heater.
- (2) Allows the heater to be preset to a lower voltage in anticipation of aging.
- (3) Enables setting the upper limit of power applied to the load.

• Comparison of temperature control characteristics when combined with a temperature controller









■ Feedback control method (PWMAPR-M, PWM-APR, APR-V)

An APR without a feedback function outputs voltage in proportion to the output setting, but the output voltage and output current may vary due to power supply voltage fluctuations and load fluctuations.

There are also loads such as those of pure metal heaters that draw several to ten times their rated current at low temperatures.

Feedback control is a function that monitors the output status of the APR and automatically corrects the output so that the output is always as specified.

The APR-V series offers the following feedback control methods to meet application needs.

*PWMAPR-M is standard (switchable using the main unit setting). The PWMAPR-M series supports B, C, and D as standard (switchable using the main unit setting). PWM-APR supports C only.

*Select "E" for APR-V if "F" was used for APR-N.

Control method	Required external devices (sold separately)	Code	Control method overview
No feedback function	-	т	No built-in CT. (No overcurrent detection, heater disconnection detection, etc.) Applied to loads with little resistance change, such as alloy heaters.
AC CLR	-	A	CLR = Current limit regulation: Limits output voltage so that output current does not exceed the CLR setting. Applied to applications for limiting the maximum current flowing to the load (e.g., pure metal heaters, etc.).
AC ACR + AC CLR	-	В	ACR = Automatic current regulation: Controls the flow of output current in proportion to the set value. Applied to pure metal heaters, direct current heating applications, etc. to maintain a constant current.
AC AVR + AC CLR	VT (Type: PT-5S) single-phase: 1 unit VT (Type: PT-5S) three-phase: 2 units	С	AVR = Automatic voltage regulation: Controls the output voltage in proportion to the set value. Applied to applications that require output voltage accuracy.
AC AWR + AC CLR	VT (Type: PT-5S) single-phase: 1 unit VT (Type: PT-5S) three-phase: 2 units	D	AWR = Automatic wattage regulation: Controls the output power in proportion to the set value. Applied to silicon carbide heaters and sensorless applications that control the heating amount.
DC feedback control + AC CLR (Feedback input: 0 to10 V DC)	Insulation converter (Fast-response product)	E	Applied when the secondary side of transformers, rectifiers, etc. require accuracy. Controls the feedback value to be 10 V DC when the set value is 100%.
Cycle control based Transformer primary control	Accessory CT (Type: CT-5S)	Р	Single phase only. Can be applied to insulation transformers and resistive loads (resistance change 20% or less). If the load is 30% or less of the APR rated capacity, output will stop due to a load error.

Advantages of AC CLR

· Advantages of selecting APR rated current

When selecting an APR, capacity should be selected considering safety factors such as the power supply voltage fluctuation +10%, temperature change in heater resistance +10%, and heater production error +10%. However, for APRs with CLR, selection can be made based on load rating because the actual output current is monitored to limit output.

- · Expected to extend heater life by limiting the current flowing through the heater to within the rated value.
- · Greatly reduces the possibility of damage due to fast fuse breakage or overload by using output current limiting and overcurrent detection functions.

• Feedback control example

Fig.1 shows an automatic voltage regulator for a DC power supply. In this circuit, the APR performs primary control of the transformer on the AC side.

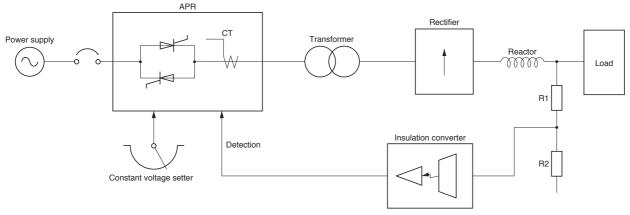


Fig.1 Automatic voltage regulator for DC power supply

The output voltage setting of the APR uses a variable resistance setting. The output voltage is supplied to the load through the transformer, rectifier, and reactor. The DC voltage divided between resistors R1 and R2 connected in front of the load is converted to a voltage insulated from the load side by an insulating converter. This voltage is then input to the APR as a detection value.

APR control uses DC automatic voltage regulation because the DC voltage detection value is input to the set value by the variable resistance setting. The variable resistance setter then serves as the constant voltage setter. The purpose of this control is to always maintain a constant voltage with respect to power supply voltage fluctuations and load fluctuations.

The above is an example of DC automatic voltage regulation. If the circuit is configured to detect DC current, convert it to an insulated voltage, and input it to the APR, it serves as DC automatic current regulation.

If AC voltage (current) is used as the detection input to the APR instead of detection from a DC circuit as described above, AC automatic voltage regulation (AC automatic current regulation) will be performed.

In other words, the control method is determined based on what is input (feedback) to the APR for detection.

Precautions for each load type

APRs can be used for resistive loads (heater loads) and other loads, but the following precautions must be taken: Special attention should be paid to heater loads because the resistance value can vary greatly depending on the heater type and operating temperature, and the resistance values can change due to aging.

• APR selection guidelines

Load type		Model selection guidelines			
Resistive load	Nichrome/ferrochrome system	In this system, all models can be used because the resistance change is not very large.			
Resistive Ioad Syr (Heater) "Refer to Table 1. Sil Sil Carter of Table 1. Sil Sil Carter of Table 1. Sil	Pure metal system	Pure metal systems have a fairly low resistance at room temperature. (Several to dozens of times the rating), so be sure to set current limit regulation (CLR).			
	Silicon carbide	Silicon carbide changes considerably with aging. This can cause it to reach 3-4 times its initial resistance over its lifetime. Generally, a transformer with a tap is used to change the voltage accordingly over time. If a transformer is not used, the output value of the APR can be changed as the load changes over time, by performing current limiting or by using a gradient setter. The recommended control method is automatic wattage regulation (AWR). With this control system, the control follows the load changes over time and always applies a constant amount of power to the load to maintain a high level of control accuracy.			
	Carbon	Carbon is used in vacuum furnaces. Load shorting may occur in vacuum furnaces. The protection for load short-circuit is a fast-acting fuse, but if there is a current limiting function, the overcurrent gate-off function will also operate, so there are cases where the gate-off function can operate and provide protection without the fast-acting fuse blowing. For this reason, current limit regulation (CLR) is recommended.			
Transformer pr	imary control	The start-up sequence is important for transformer primary control. A start-stop signal and soft-start function need to be used to slowly increase the output voltage. In addition, it is necessary to investigate what will be connected to the load to determine the suitability of the model and the control method. If the secondary side of the transformer is open, a bleeder resistor must be added to the primary side to ensure stable control. The reason for this is that if the no-load current of the transformer is small, the thyristor cannot be ignited (turned ON) and only one side of the transformer will be controlled, and a large DC current will flow to the primary side of the transformer, which may cause the fast-acting fuse to blow or the thyristor to break. This abnormally large transformer primary current is called the "bias magnetism phenomenon".			
Inductive load		The load current flows with a delay relative to the power supply voltage, so please pay attention to the model to be applied. Models with transformer primary control can handle this inductive load. Also, in the APR capacity calculation, the load capacity should be kVA, not kW.			
Rectifier prima	Rectifier primary control What is connected to the load is important in rectifier primary control. In general, rectifier primary control requires a transformer in the previous stage and is performed w automatic voltage regulation (AVR) or automatic current regulation (ACR).				
Capacitive load	d (capacitor load)	It is not applicable for phase control APRs, but it can be used with our PWMAPR-M series. For example, it can be used for simple capacitor banks.			

• Applicable models for various loads

Based on the above, the applicable models and recommended control methods for various loads are as follows.

Load type		Applicable models	Recommended control method		
Resistive	Nichrome/ferrochrome system	All models	All control methods		
load	Pure metal system	PWMAPR-M, APR-V, single-phase APR-D	Addition of CLR (A); ACR (B)		
(heater)	Silicon carbide system	PWMAPR-M, APR-V, single-phase APR-D	Addition of CLR (A); AWR (D)		
	Carbon	PWMAPR-M, APR-V, single-phase APR-D	Addition of CLR (A)		
Transformer	primary control	PWMAPR-M, APR-V, single-phase APR-D	Addition of CLR (A)		
Inductive loa	d	PWMAPR-M, APR-V, single-phase APR-D	Addition of CLR (A)		
Rectifier primary control		PWMAPR-M, APR-V, single-phase APR-D	Addition of CLR (A)		
Capacitive lo	ad (capacitor load)	PWMAPR-M	-		

Table 1. Classification of heating elements

	Alloy system and carbon system	Pure metal system	Silicon carbide system			
Type and maximum	Nichrome 1100°C *	Molybdenum 1800°C *	Silicon carbide			
operating temperature	Ferrochrome 1200°C	Tungsten 2400°C *	Amorphous carbon			
Product name in	Graphite	Platinum 1400°C	(Tecorundum) 1600°C *			
parentheses ()	(Kanthal) 1300°C *	(Kanthal Super) 1700°C *	(Siliconit) 1600°C *			
	(Kanthal A-1) 1375°C *		(Erema) 1600°C *			
	(PyroMax) 1300°C					
Resistance temperature characteristics (example)	Boot to the second seco	100 80 60 90 90 90 90 90 90 90 90 1,200 1,500	$\begin{array}{c c} \hline & 100 \\ \hline & & 80 \\ \hline & & & 60 \\ \hline & & & & \\ \hline & & & & \\ \hline & & & & \\ \hline & & & &$			

* atmospheric conditions



APR Series selection

The following items must be confirmed in the selection process.

Item	Content									
Waveform control method?	PWM control (amplitude of sine wave), cycle control (ON/OFF for sine wave unit), phase control (change of conduction phase in sine wave)									
Number of power phases?	Single phase or three phase									
Voltage?	100 V system, 200 V sys	tem, 400 V system								
Current?	20 A, 45 A, 60 A, 100 A,	etc.								
Setting method?	Manual (variable resistar	nce), Automatic (4 to 20 mA, etc.)								
Type of load?	Resistive load	Alloy systems and carbon heaters (Those with resistance change of 10% or less due to temperature change)	Nichrome (including far-infrared), nickel, ferrochrome, graphite (Kanthal A, etc.)							
		Pure metal heaters, lamps (Those with a large resistance change of several to dozens of times due to temperature change)	Tungsten (Including incandescent lamps and halogen lamps), platinum,molybdenum, tantalum, ceramic, (Kanthal Super, etc.)							
		Silicon carbide heaters (Those with a resistance increase due to aging that is 3-4 times the initial value)	Silicon carbide, amorphous carbon (Erema, Siliconit, Tecorundum, etc.)							
	Inductive load	Magnetizers, vibrators, etc.								
	Capacitive load	Capacitors, etc.								
	Transformer primary control	When a transformer is connected to the APR for resistive and inductive loads								
	Rectifier primary control	When a diode rectifier is connected to the APR as a DC p	power supply (LED lamp)							
Feedback function?	CLR Constant voltage, consta	nt current, constant power								

APR Series Comparison Summary List

(\bigcirc : Verv good \bigcirc : Good \triangle : Normal)

Al IN Genes Companson Summary List	(©. very	
Series name	Function	Compact and lightweight
Single-phase PWMAPR-M, three-phase PWM-APR	0	\bigtriangleup
Single-phase APR-V, three-phase APR-V	0	
Single-phase APR-D, three-phase APR-D	0	0

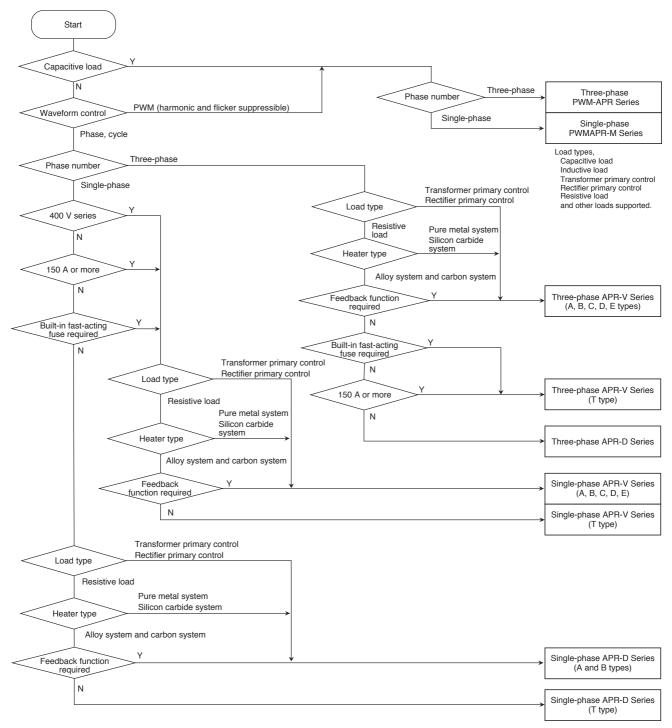
*KANTHAL® is a registered trademark and a trademark of the Sandvik Group.

*EREMAL[®] is a registered trademark and a trademark of Tokai Konetsu Kogyo Co., LTD. *SiliconitL[®] is a registered trademark and a trademark of Tokai Konetsu Kogyo Co., LTD. *PYROMAXL[®] is a registered trademark and a trademark of Riken Corporation.

Delivery dates

Please inquire about delivery date.

Series selection flowchart





Features, applications, series configuration

Series name	Applications	Features	Appearance	Series					
				Туре	Input voltage				
Single-phase PWMAPR-M Three-phase PWM-APR	Test facility/laboratory facility, etc. high-precision constant- voltage power supplies Rectifier-combined high-precision DC power supplies Locations with poor power supply conditions (Voltage fluctuation) stabilization power supplies Heater control Dimming of various lights	Utilizes IGBT-equipped PWM control method to achieve sine wave output No need for harmonic suppression measures		RPME2□□-M RPWD2□□-1C■	200-240 V 200-220 V				
Single-phase APR-V	Heater control Dimming of incandescent lamps and LEDs Vibrators Rectifier-combined DC power supplies	 Multifunction Various applied loads Various feedback control functions Various current and voltage types 		RPVE2	100-240 V				
_		Phase control/cycle control Built-in fast-acting fuse		RPVE4	380-480 V				
Three-phase APR-V				RPVW2	100-240 V				
				RPVW4	380-480 V				
Single-phase APR-D	Heater control Dimming of incandescent lamps	 Inexpensive Compact and lightweight Various setting inputs Various applied loads Phase control/cycle control 		RPDE2□□-□■	100-240 V				
Three-phase APR-D	-		200 100 100	RPDW2□□-T■	200-240 V				
				RPDW4□□-T■	380-440 V 380-480 V (Operating transformer sold separately)				

Rated output current [A]															
6	10	20	30	40	45	60	80	100	150	160	250	350	450	600	Reference page
		•					•			•	● (240 A) P22 PWM- APR				12
				● P22 PWM- APR			● P22 PWM- APR			● P22 PWM- APR					
		•			•	•		•	•		•	•	•	•	22
		•			•	•		•	•		•	•	•	•	
		•			•	•		•	•		•		•	•	
		•			•	•		•	•		•		•	•	
		•			•	•		•							40
		•			•	•		•							46
		•			•	•		•							



New release of PWMAPR-M as digitally controlled PWMAPR

Expands the range of applications to include applications that were not possible with conventional power regulators

Features

Uses our proprietary PWM control method to eliminate the need for harmonic current countermeasures

- Saves energy because it does not deteriorate the load power factor
- Capable of being used as a test power supply thanks to its sine wave output
- Comes standard with VLR function (voltage limiting) effective for lamp loads, etc.
- Comes standard with setting indicator as a new feature*1
- Volume: 36% reduction, Mass: 40% reduction, Footprint: 25% reduction compared to conventional products
- Slots available for various communication units^{*2} and analog/ digital IO boards
- Lineup of products compliant with overseas standards *80 A products only (as of July 2023)

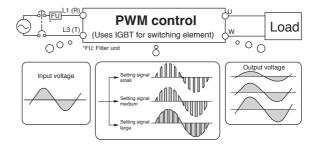


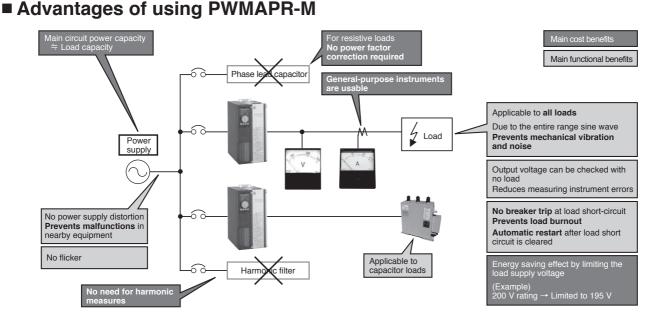
Compliant with the new EMC Directive (2014/30/EU) Compliant with the new Low Voltage Directive (2014/35/EU)

*1: Feedback methods such as automatic current regulation (ACR), automatic voltage regulation (AVR), automatic wattage regulation (AWR), as well as gradient settings are also available.
*2: Modbus RTU, CC-Link, etc.

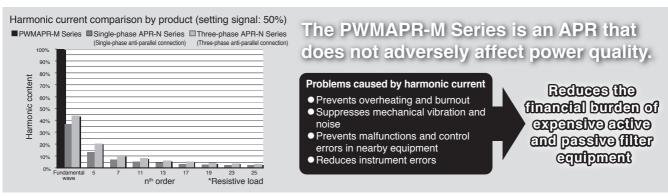


Operating principles





Advantage of not generating harmonic current



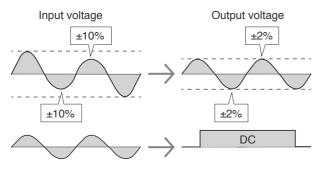
Examples of various applications unique to the PWMAPR-M series

• Outputs a clean sine wave at any output range



With PWMAPR-M, you can produce a clean sine wave^{*} at any output range (no transformer for tap-switching is needed). *The output waveform depends on the input waveform. The distortion rate is also affected by input and output. For details, see the "Distortion rate" on page 15.

Achieves stable output voltage



With PWMAPR-M, you can always produce a stable output ($\pm 2\%$ FS* output even if the input voltage fluctuates $\pm 10\%$).

It is also perfect for more advanced DC power control when combined with a rectifier.

* It does not come with a boost function. It may not be effective if the input voltage and the set output voltage are the same (close).

*It does not support instantaneous power failures, etc.

For **product inspection testing facilities** that require stable output!

For locations with **voltage fluctuations**, such as overseas where power supply conditions are not good!

Since it does not contain a battery, it is expected to have a longer maintenance cycle.

Of course, it also supports conventional applications, such as heater control, with high accuracy.



Unlike waveform control, which uses a thyristor device for switching, PWMAPR-M does not generate harmonics or exhibit flicker, nor does it deteriorate the power factor. In addition, since the output waveform is clean, it is less prone to exert stress on the load (heater, etc.) and can be expected to extend the life of the load. ("Japanese Guideline for Suppressing Harmonics by Customers Receiving High Voltage or Special High Voltage" Conversion factor K5/K6 = 0, Power factor = 1) General-purpose products (not special devices) can be used to measure output voltage, current, etc.

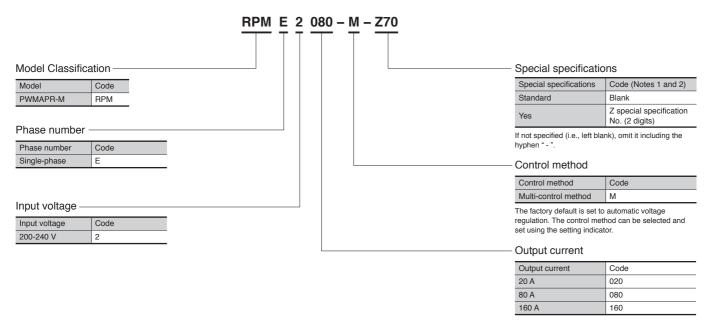
No need for expensive harmonic countermeasures

Energy saving thanks to no power factor deterioration

Economical thanks to ability to use general-purpose instruments



Order specifications (explanation of order types)



(Note 1) List of special specifications

Option specification name	Contents	Туре
Printed wiring board coating process	Comes with a printed board coated with a coating agent	RPME2

(Note 2) Please contact us about product types compliant with international standards.

Other options (sold separately)

Product name	Туре	Specifications
Setter (Note 3)	RPN001	1 k Ω J, 2.5 W with nameplate, knob, and name label sheet
Remote control connection	RPN002-1	Setting indicator For separate installation, length 1 m
cable	RPN002-3	Setting indicator For separate installation, length 3 m
A/D IO board	RPM003-AA	Analog/digital I/O board
Communication	RPM003-AM	Modbus RTU compatible
unit	RPM003-AC	CC-Link compatible

(Note 3) The setter (used for manual setting, gradient setting, HIGH setting, etc.) is ordered separately.

Rating, type (= product code)

Phase	Input voltage [V]	Rated current [A]	Rated load capacity [kVA] (Note 4)	Type (= product code)
number				
Single-phase	200-240	20	4-4.8	RPME2020-M
		80	16-19.2	RPME2080-M
		160	32-38.4	RPME2160-M

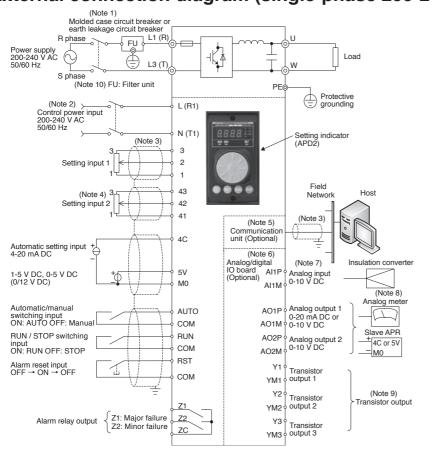
(Note 4) The rated load capacity is the value calculated by the rated voltage X rated current. *The release dates and other details for products with specifications not listed in the table above will be announced separately.

Specifications

Iter			Specifications		· · · ·			
	in circuit power		Single-phase: 200-240 V AC 50/60 Hz	± 2.5 Hz (frequency automatically detern	nined)			
ten	nperature 40°C	gle phase (ambient)		80 A	160 A			
	oling system		Air cooling					
	ntrol circuit	Power supply voltage	Single phase: 200 V AC - 240 V AC ± 1	0% 50/60 Hz ± 2.5 Hz				
	wer supply	Power capacity	25 VA	450.34	000.14/			
		alue [W] (at rated current)	I	450 W	900 W			
_	plied load			e load, transformer primary control, recti	tier primary control			
	Waveform con		Sine wave output according to PWM co					
	Output voitage	e adjustment range	0-97% (input voltage = relative to filter	unit output voltage)				
	Distortion rate (Note 1)		5% or less (resistive load, output voltag	e 50% or higher)				
		Output current distortion rate	5% or less (resistive load, output voltag		the second for the local At-			
	Input-output cl		automatic setting signal 10-90%)	characteristic $\pm 2\%$ FS or less (Limited to				
		e control method		(3) Digital setting using the setting indic	ator			
2	Soft start time		Digital setting using the setting indicato		v 0.1.100 accordo			
ocurido	Soft up/down t	ume setting		p time: 0.1-100 seconds, Soft down time	2: 0.1-100 seconds			
5	CLR (current I	imit regulation) settings) Setting by external variable resistor: 1 k Ω	(B characteristic 2.5 W) (1) and			
			are switchable using the setting indicator. 0-100% of the output voltage					
	VI B (voltage l	imit regulation) setting	1 0) Setting by external variable resistor: 1 kΩ	(B characteristic 2.5 W) (1) and			
	v Lin (voltage i	init regulation) setting	are switchable using the setting indicator.	J Certing by external variable resistor. T KL				
	P adjustment		Digital setting using setting indicator Pro	oportional gain: 0.1-0.5x				
I	I adjustment		Digital setting using setting indicator Int	· · ·				
		nection detection setting	Digital setting using the setting indicato	0				
	Tieater discon	nection detection setting	Output voltage \times 0-100%	1				
Gradient settings			 (1) Digital setting using setting indicator (2) Setting by external variable resistor: 1 kΩ (B characteristic 2.5 W) (3 1-5 V DC signal 					
	Base load sett	lina	(1) to (3) are switchable using the setting indicator 0-100% of the output voltage					
Manual setting			Digital setting using setting indicator Reverse gradient characteristic is possible when combined with gradient (1) Digital setting using setting indicator (2) Setting by external variable resistor: 1 kΩ (B characteristic 2.5 W) (1) and (are switchable using the setting indicator.					
	Automatic sett	·	Current signal: 4-20 mA DC (Zin = 100 Ω), Voltage signal: (1) 0-5 V DC, (2) 1-5 V DC (Zin = 11 k Ω)					
			SSC signal: $0/12 \text{ V DC}$ (Zin = 11 k Ω)					
RUN / STOP switching signal (RUN) Auto / manual switching signal (AUTO) Alarm reset signal (RST)			No-voltage contact input (15 V DC, sink current: 10 mA)					
		switching signal (AUTO)	No-voltage contact input (15 V DC, sink					
2	Alarm reset sig	<u> </u>		15 V DC sink current: 10 mA), or setting	Indicator			
	Network comn	nunication	Modbus RTU, CC-Link					
-	play		Digital setting using setting indicator					
_	rm contact out	put		, 250 V AC, 1 A), minor failure (1a contac				
	Overcurrent		stop operation: Factory default setting)	rrent to the load exceeds the overcurrent				
5	Overheating	rror		current (peak value) detected by built-in				
	Overheating e			e main circuit exceeds the allowable temp	Halule.			
J	CPU memory			ected at the startup of the control circuit.				
	Communicatio		· · · · ·	communication unit (optional) is not nor				
	Heater discon	nection		ue drops below the disconnection thresh				
		ircuit not connected (Note 2)	(2) When manual/gradient settings are		ss than 4 mA or less than 1 V)			
	Power supply	error	It operates when the power supply frequencies					
	Current limit a	nd voltage limit	It outputs an alarm when it detects the s value).	same load current (output voltage) value	as the CLR set value (VLR se			
	Main circuit fu	se blown	Output stops when the fuse in the main					
	Cooling fan life	Э	It displays an alarm when it falls below	70% -200 rpm of the steady state speed				
I	Power supply	low voltage	It operates when the main circuit power	supply drops below 175 V.				
J	Power supply	overvoltage	It operates when the main circuit power	supply rises above 276 V.				
ee	edback control		AC ACR (Automatic current regulation) AC AVR (Automatic voltage regulation AC AWR (Automatic wattage regulation DC feedback control) (Types with control method C)	* Control methods can be switched using the setting indicator. * For types with control methods B, 0 and E, AC CLR (VLR) is prioritized			
	Ambient temp	erature	-5 to +40°C (Reduced relative to rated	current value when above +40°C and be	low +55°C)			
	Storage tempe		-20 to +60°C					
5	Ambient humi		30-90% RH (no condensation)					
	Others			nd actions that promote insulation deteri	oration, or vibration; Use indoc			
	Dielectric stren	ngth (Main circuit to ground)	2000 V AC for 1 minute					
IIIIIIIIIIIIIIIIIIIIIIIIIIIIIIIIIIIIIII	Insulation resi	stance (To ground)	10 M Ω or higher, measured with 500 V	DC megger tester				
1								

(Note 1) This is the value when the distortion rate of the power supply voltage is 1% or less. (Note 2) It does not operate when the voltage signal 0-5 V DC (SSC signal: 0/12 V DC) is set. (Note 3) When DC feedback control is selected, an A/D IO board (type: RPM003-AA) is required.

■ External connection diagram (single-phase 200-240 V AC)



- (Note 1) In order to protect the wiring on the input side (primary side) of the APR, install the molded case circuit breaker or earth leakage circuit breaker (with overcurrent protection) recommended for each APR. Do not use circuit breakers that exceed 1.5 times the product rating.
 (Note 2) Keep wires as far away as possible from
 - other control terminal wiring and do not place them in the same duct. When crossing other control terminal wires, make sure that they are nearly orthogonal.
- (Note 4) Setting input 2 can be set to gradient setting input, CLR setting input, or VLR setting input using APD2.
- (Note 5) The communication unit is optional. (Note 6) The A/D IO board is optional. (Note 7) The analog input is used to apply types
- (Note 7) The analog input is used to apply types with control method E. Input the analog signal of 0-10 V DC that was output from the insulation converter, etc.
 (Note 8) Analog output is performed by converting
- the output voltage, output current, or output power of the APR into a current signal or voltage signal and outputting it. (Note 9) The transistor output is performed by
- (Note 9) The transition output is performed by outputting the APR alarm status.
- (Note 10) Be sure to use one filter unit (accessory) for each PWMAPR-M unit.

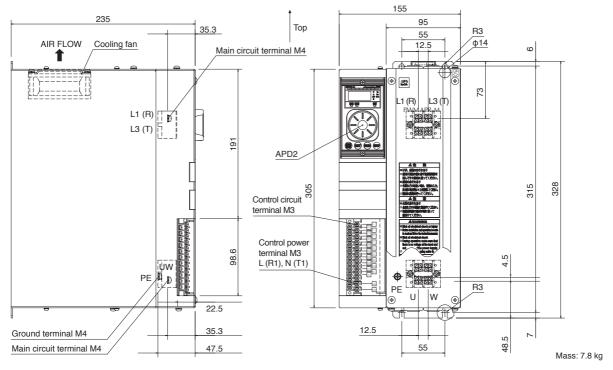
Terminal function (single phase)

Terminal position	Symbol	Name	Function description
Filter unit	IN	Input terminal	Main circuit input (connected to power supply)
Main circuit terminal	OUT	Output terminal	Filter unit output [connected to L1 (R)]
PWMAPR-M	L1 (R)	Input terminal	Filter unit input [connected to OUT]
Main circuit	L3 (T)		Main circuit input (connected to power supply)
terminal	U	Output terminal	PWMAPR-M output (connected to load)
	W]	PWMAPR-M output (connected to load)
	⊕(PE)	Ground terminal	Main body grounding terminal Be sure to ground the ground.
Control Terminal	1, 2, 3	Setting input 1	It can be used as a manual setting input, current limit setting input, voltage limit setting input, or LOW setting by connecting a variable resistor.
	41, 42, 43	Setting input 2	It can be used as a gradient setting input, current limit setting input, voltage limit setting input, or HIGH setting by connecting a variable resistor.
	4C, M0	Automatic setting input	Current signal 4-20 mA DC input, such as a temperature controller
	5V, M0	Automatic setting input	Voltage signal 0-5 V DC, 1-5 V DC input, such as a temperature controller, or SSR signal 0/12 V DC input Voltage signal 1-5 V DC input can be assigned to gradient setting input
	AUTO, COM	Automatic/manual switching input	Automatic setting when the external contact is closed Manual setting when the external contact is open
	RUN, COM	RUN / STOP input	RUN state when the external contact is closed Output off (STOP) state when the external contact is opened
	RST, COM	Alarm reset input	Resets alarm display and alarm contact output when the external contact is closed
	Z1, ZC	Alarm contact output	Internal contact ON when alarm occurs (major failure)
	Z2, ZC	Alarm contact output	Internal contact ON when alarm occurs (minor failure)
	L (R1)	Control power supply terminal	Power input for control circuit (connected to power source)
	N (T1)	Control power supply terminal	Power input for control circuit (connected to power source)

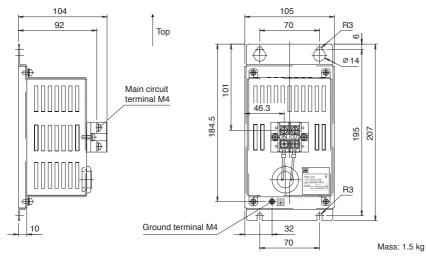


External dimension diagram [Unit: mm]

• RPME2020-M (single phase 200-240 V AC rated 20 A)



• Single phase 20 A filter unit

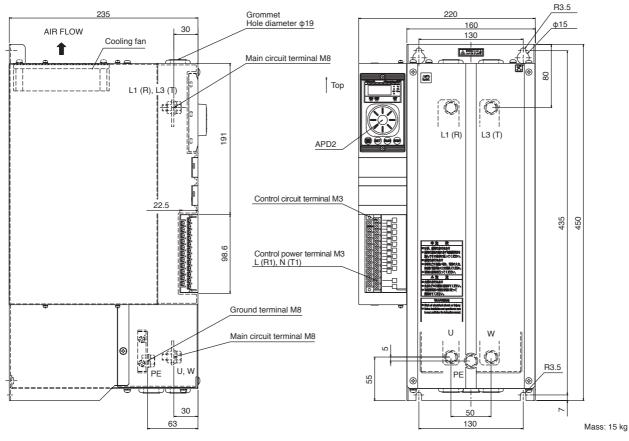


*A filter unit is included as standard. Be sure to install it and connect it to the APR primary side.

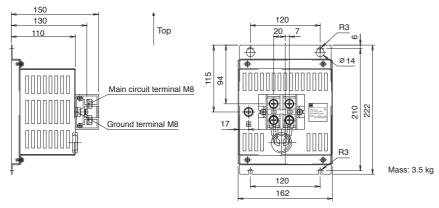


External dimension diagram [Unit: mm]

• RPME2080-M (single phase 200-240 V AC rated 80 A)



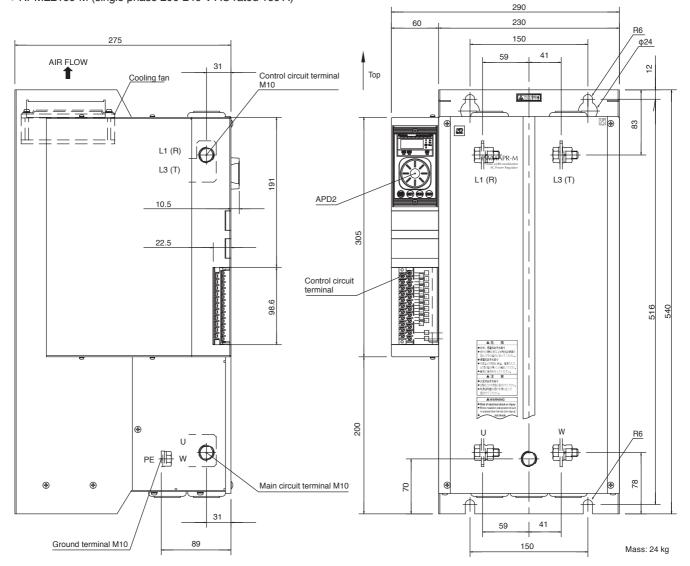
• Single phase 80 A filter unit



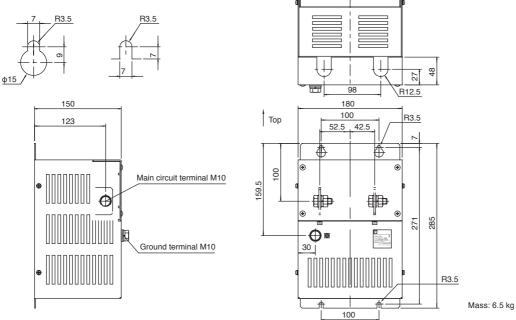
*A filter unit is included as standard. Be sure to install it and connect it to the APR primary side

External dimension diagram [Unit: mm]

• RPME2160-M (single phase 200-240 V AC rated 160 A)



• Single phase 160 A filter unit



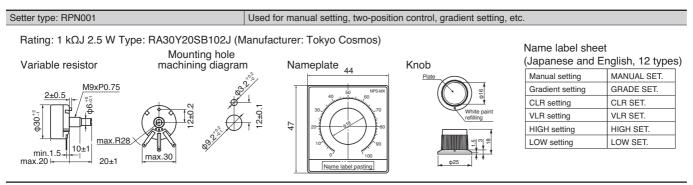
*A filter unit is included as standard. Be sure to install it and connect it to the APR primary side.



Terminal screw size (single phase)

Terminal		Termin screw			ening torque] ±10%
Main circuit	L1 (R), L3 (T), U, W,	20 A:	M4	1.8	(18 kg·cm)
input/output	IN, OUT	80 A:	M8	13.3	(135 kg·cm)
terminal			M10	24	(245 kg·cm)
Ground	round (PE)		M4	1.8	(18 kg·cm)
		80 A:	M8	13.3	(135 kg·cm)
		160 A:	M10	24	(245 kg·cm)
Control power supply	L (R1), N (T1)	M3		0.5	(5 kgf·cm)
Control terminal	Other than the above	MЗ		0.5	(5 kgf·cm)

Separately sold



Setting indicator enables multiple settings not available in other company products!!

Features

- Various types of feedback control are available without adding extra options. (AVR/ACR/AWR, CLR/VLR)
- The LED monitor displays various types of information such as output voltage, output current, output power, power supply voltage, output setting signal,% display, etc. Setting and display of various alarms are also very accurate because they are digital.
- The multi-indicator provides visual status confirmation.
- Features a dial to make various settings more user-friendly. It can also be used as an alternative to gradient setting volume, etc.
- Enables setting of various network parameter settings. (Modbus RTU/CC-Link)
- Comes with a heater disconnection detection function as standard. (Capable of detecting one disconnection for every five alloy heaters)
- Mountable to panel surfaces, etc., using a remote control connection cable (RPN002-1 or RPN002-3).



*This product is a standard accessory.

Operation mode			SET mode		MON (monitor) mode					
Dis	play unit and o	operation unit		RUN/STOP	Running	RUN/STOP	Running			
Display unit	Multi Indicator		Function	When the multi-indicator is fixed, each type of operation information, communication monitor, etc. is displayed in 8 segments						
spla	Indicator		Display	ON/Blinking						
Diá	LED	0000	Function	Function code and function	Function code and function code data display Displays operation voltage and output					
	monitor	8.8.8.8.		When an alarm occurs, it	displays an alarm code					
			Display	ON						
			Function	Displays various states						
	Status	RUN MON NET	Display	•RUN-LED OFF	•RUN-LED ON	•RUN-LED OFF	•RUN-LED ON			
	display			•MON-LED OFF		•MON-LED ON				
				NET-LED Setter: ON when NET (network) mode is selected						
			Function	Displays the unit of data	displayed on the LED mon	itor				
		V %	Display	•V-LED Voltage display						
	A Hz		•A-LED Current display							
	Unit display			•kW-LED Power display						
		Ω		•%-LED Percent display						
				•Hz-LED Frequency	1 7					
				Sec-LED Setting time	display					
Operating unit	Dial		Function	Function code and increa	ase/decrease of function	Switching the display mode of each type of operation information				
era	MODE/	MIDE	Function	Change to MON (monitor) mode	Change to SET mode				
do	RESET key	RESET				RESET after removing e	error cause			
	SET key	SET	Function	Displays function code da	ata and sets data		-			
	RUN key	RUN	Function	RUN start	-	RUN start	_			
	STOP key	STOP	Function	_	RUN/STOP	-	RUN/STOP			

Display and key operation



The APR-V Series is the successor to the APR-N Series. It is a highly functional APR with improved functions and performance and maintains installation and wiring compatibility.

Features

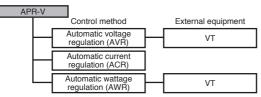
- Switchable between phase control and cycle control · Capable of load-sharing using anti-flicker cycle control (staggered energization cycles for up to 50 units). (Optional specifications: ZAP or ZAX required)
- · Enables cycle control for loads with large resistance fluctuations (e.g., pure metals) by using an automatic rush current suppression function (combined control) that is independent of the soft start time. (Types with control method A only)
- · Allows switching between phase control and cycle control while runnina.

(By setting indicator (APD3), network communication, etc.)

 Built-in high-precision feedback control function (except types with control method T)

Achieves control accuracy of ±1% FS for automatic current regulation, automatic voltage regulation, and automatic wattage regulation.

Contributes to improved temperature control accuracy, space savings, wiring savings, and total cost reduction by incorporating a high-precision control circuit.



- Supports imbalance correction (three-phase) If there is load imbalance or power supply imbalance, the
 - imbalance can be corrected by setting the setting indicator (APD1).
- Supports three-phase four-wire circuits (three-phase, control methods T and A types only)

Achieves ±3% FS linearity in three-phase, four-wire circuits. (Optional specification: Please specify ZB4)

In addition, it does not require an external diode connection to the neutral phase.

- (Note) Do not use in a three-phase, three-wire circuit, since the control phase angle is different from that of three-phase standard products.
- Enables individual setting of soft start time and soft up/down times
- Does not require a 400 V system operating transformer Allows operation using a 200 V power supply, since it does not require a dedicated operating transformer for the control power input of 400 V products.

(Can perform control even if the main circuit power supply and control power supply are not of the same phase)







Single-phase 20 A

Single-phase 20 A Setting indicator (APD3) Main unit connection

Single-phase 20 A Setting indicator (APD3) Cable connection



Three-phase 20 A







Three-phase 100 A With communication board (ZAP)

• External dimensions and mounting dimensions are compatible with APR-N

Three-phase 20 A

Setting indicator (APD3)

Main unit connection

External dimensions, mounting dimensions, and wiring positions are 100% compatible with those of the APR-N Series.

 Does not require a communication board for setting indicator (APD3) connection

Comes standard with a dedicated APD3 connector on the front panel.

Connection can be made with a single cable.

• Full lineup of options

- \cdot Enables a variety of monitors and high-precision digital settings and function settings using the setting indicator (APD3)
- · Supports various communication specifications using additional communication boards.

Makes it easy to operate, monitor, and change settings by linking with PLCs and touch panels.



Setting indicator (APD3)

Capable of analog output of operation status Capable of outputting the present operating status (output current,

- output voltage, etc.) using analog signals (4 to 20 mA DC, etc.).
- · Capable of outputting a contact point for power-on confirmation · Finger guard (IP20)

and others

• Built-in high-performance heater disconnection detecting function (except types with control method T. The function requires setting indicator (APD3))

Single phase can detect up to 1-wire/10-wire disconnections using the high-function heater disconnection detecting function (equivalent to LA-3AR).

Three-phase three-wire types can detect up to 1-wire/9-wire disconnections.

(Line current detection method)

Three-phase four-wire types can detect up to 1-wire/15-wire disconnections.

(Line current detection method)

Applicable to various types of heaters (alloy, pure metal, silicon carbide, etc.) of the same material and capacity.

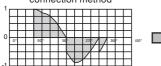


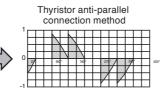
(Note) Single-phase requires one external CT.

• Standardized thyristor pure anti-parallel system (six-arm) (three-phase)

- Since it generates almost no even-order harmonic currents, it makes it easier to implement harmonic current countermeasures than with mixed anti-parallel systems.
- Transformer primary control reduces the likelihood of the phenomenon of bias magnetism, thus allowing transformers to be made smaller and more efficient.
- · Improves control characteristics under unbalanced loads.

E.g. of load current waveform (phase angle a = 90°) Mixed anti-parallel connection method





• Enhances abnormality detection

Displays twelve types of failures, including major and minor ones, using its alarm LEDs.

- · Thyristor abnormalities (except types with control method T)
- \cdot Current limit detection (except types with control method T)

 \cdot External setting input not connected (disconnection) and others

• Compliant with the EU RoHS Directive (2011/65/EU+(EU)2015/863)

Complies with the EU Restriction of Hazardous Substances (RoHS) Directive as standard.

It is an environmentally friendly APR that restricts the use of the 10 hazardous substances

<10 Hazardous Substances>

Lead, mercury, cadmium, hexavalent chromium, polybrominated biphenyls (PBB), polybrominated diphenyl ethers (PBDE) Phthalates (DHEP, BBP, DBP, DIBP)

• Complies with revised Chinese RoHS All APR-V Series models are supported as



· Lineup of products compliant with overseas standards



standard.

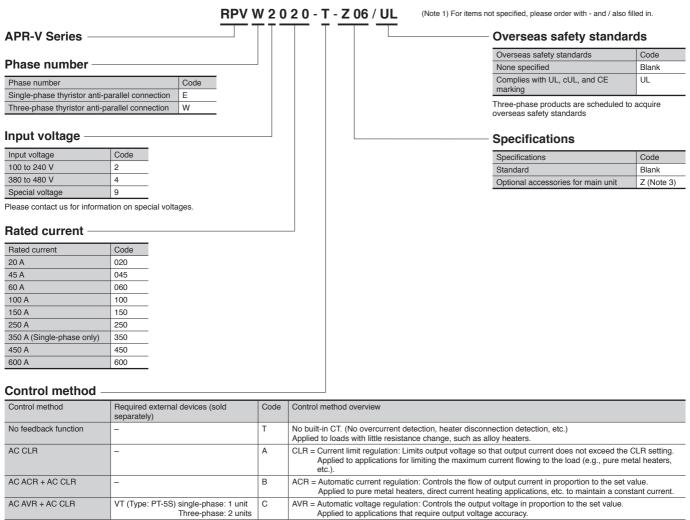
Compliant with the new EMC Directive (2014/30/EU) Compliant with the new Low Voltage Directive (2014/35/EU)

(Note) Please contact us for information on acquisition status.



APR-V Series

Order specifications (explanation of order types)



			Applied to loads with little resistance change, such as alloy heaters.
AC CLR	-	A	CLR = Current limit regulation: Limits output voltage so that output current does not exceed the CLR setting. Applied to applications for limiting the maximum current flowing to the load (e.g., pure metal heaters, etc.).
AC ACR + AC CLR	-	В	ACR = Automatic current regulation: Controls the flow of output current in proportion to the set value. Applied to pure metal heaters, direct current heating applications, etc. to maintain a constant current.
AC AVR + AC CLR	VT (Type: PT-5S) single-phase: 1 unit Three-phase: 2 units	С	AVR = Automatic voltage regulation: Controls the output voltage in proportion to the set value. Applied to applications that require output voltage accuracy.
AC AWR + AC CLR	VT (Type: PT-5S) single-phase: 1 unit Three-phase: 2 units	D	AWR = Automatic wattage regulation: Controls the output power in proportion to the set value. Applied to silicon carbide heaters and sensorless applications that control the heating amount.
DC feedback control + AC CLR (Feedback input: 0 to10 V DC)	Insulation converter (Fast-response product)	E	Applied when the secondary side of transformers, rectifiers, etc. require accuracy. Controls the feedback value to be 10 V DC when the set value is 100%.
Cycle control based Transformer primary control	Accessory CT (Type: CT-5S)	Р	Single phase only. Can be applied to insulation transformers and resistive loads (resistance change 20% or less). If the load is 30% or less of the APR rated capacity, output will stop due to a load error.

(Note 3) Optional accessories for main unit

Main option specification name	Content	Option specification number (Note 4)
Soft start time minimum of 0.05 sec (applicable only to types with control methods T and A) $$	Variable soft start time range 0.05 to 10 sec/0.5 to 100 sec	RPV
Incorporates base load setting	Incorporates base load setting on control circuit PCB	RPVZ07
Incorporates gradient setting	Incorporates gradient setting on control circuit PCB	RPV
PCB coating process	Incorporates PCB with coating applied	RPV
Control power separation	Eliminates internal wiring of control power supply terminal block (L11-L21)	RPVW2
Communication board) Supports parallel run	Parallel run communication board mounting with anti-flicker function (Note 5)	RPV
Communication board) Supports MX compatible parallel run	MX, MX2 Series compatible parallel run communication board mounting (Note 6)	RPV
Communication board) Supports Modbus RTU	Modbus RTU communication board mounting (Note 7)	RPV
Communication board) Supports CC-Link	CC-Link communication board mounting (Note 7)	RPV
APD3 main unit mounting (cable connection connector accessory)	Mounts APD3 on the front surface of the main unit	RPV
Supports three-phase four-wire type	Control board change for three-phase four-wire type (types with control methods T and A only)	RPVW
Function code changed type	Shipped with the function code changed to the specified one (Note 8)	RPV
Input voltage) Supports special voltages	Supports special voltages other than rated voltage (Note 9)	RPV
Analog output board) Supports current signals	4 to 20 mA DC output Analog output board mounting (Note 10)	RPV
Analog output board) Supports voltage signals	0 to 10 V DC output Analog output board mounting (Note 10)	RPV

(Note 4)

When specifying multiple main unit options, please list the specification numbers after Z. E.g.: Order format for specifying "Soft start time minimum 0.05 sec," "Communication board) Supports parallel run," and "APD3 main unit mounting" as optional items for the main unit. Order format: RPVE

Not compatible with NX and MX2 Series. Compatible with N Series. Does not support cycle control in combination with three-phase products. The APD3 heater disconnection detection function is not available for slave units. (Note 5)

(Note 6)

(Note 7)

(Note 8)

is not available for slave units. Flicker suppression is activated during cycle control. Compatible with MX and MX2 Series. Does not support cycle control in combination with three-phase products. The APD3 heater disconnection detection function is available for slave units. Flicker suppression is activated during cycle control. Please purchase APD3 when selecting optional specification numbers ZAM and ZAC. This is required when making settings. Shipped after setting changes are made in-house using the setting indicator (APD3). The setting indicator (APD3) is not included in the shipment. Customization is available. Please contact us for more information. Please contact us regarding available input voltages.)) The output cinnal content can be changed using the APD3.

(Note 9) Please contact us regarding available input voltages. (Note 10) The output signal content can be changed using the APD3

Specifications

	-			Specification								
	oduct code)			RPV		60	100	150	050	050	450	600
lated cur	irrent [A]	Single phase (ambient tempe	· · · · · · · · · · · · · · · · · · ·	20	45	60	100	150	250	350	450	600
		Three phase (ambient temper	rature 40°C)			V 4.0. 000 i				-		
	cuit power	Power supply voltage							se 200 to 24	40 V AC, 380	to 480 V AC ±	10%
upply		Frequency				y is automatica	,	,				
ontrol ci		Power supply voltage					lowever, only	/ sine wave op	eration is g	uaranteed. M	ust operate in	phase with the
ower su vote 1)	ірріу				power supply							
		Frequency			Iz (Frequency	y is automatica	ally detected	,				
		Power capacity [VA]	Single-phase	36				40	45			
			Three-phase	39				58	72	-	72	128
ternal h	neating valu	ue [W] (at rated current)	Single-phase	47	74	89	124	190	320	377	510	700
			Three-phase	90	170	210	330	560	840	-	1490	2070
ooling s	system			Self-cooled				Air cooling				
oplied lo	oad	Phase control		Resistive loa	ad, inductive	load, transforr	ner primary c	ontrol, rectifie	r primary co	ontrol		
		Cycle control (Note 2)		Resistive loa	ad, inductive	load, transforr	ner primary c	ontrol (applica	ble to singl	e-phase contr	ol method P ty	pe only)
5 Wave	eform cont	trol method		Phase contr	ol or cycle co	ontrol (intermitt	ent) (Functio	n selection sw	itch SW2 s	vitchina)	,	,
		adjustment range				power supply	, ,					
		aracteristics									f resistive load	
Input	n-output ch	laracteristics			al 10 to 90%)	tenstic, intear o	characteristic	± 2% F3 01 16	iss (Linited	to the case o	Tesistive load	is. Al automa
Pow	or supply y	voltage compensation					fluctuations	of +10% by ro	ducina outr	ut fluctuation	s to ±3% FS or	
		types with control methods T, A	0			of automatic s			uucing out	ut nucluations	5 10 ±3 /8 1 3 01	1633 (1100060
		Manual setting	·/			: 1 kΩ (B char						
Joeilli	ing signal	manual setting				control) conta			external wir	ina		
		Automatic setting			<u> </u>	A DC (Zin = 10°	0					
		Automatic Setting				A DC (Z In = 10 DC, 1 to 5 V D0		D) (Function e	election sw	itch SW4 swite	china)	
Grad	dient setting	a				e set as desire		, ,				
	aleni setting	9				stor 1 kΩ (B ch			r) (standaro	l), (2) Built-in	(optional).	
					circuit termina				, (-,, (_)	(,	
											ts 1 to 5 V DC	only)
				Enables rev	erse gradient	t characteristic	s in combina	tion with base	load setting	9		
Base	e load setti	ng		0 to 100% o	of the output v	oltage (Optior	nal: built-in)					
Soft	start and s	soft up/down time (Note 3)		0.5 to 10 se	conds or 5 to	100 seconds	(function sele	ection switch S	W1 switchi	ng), and the s	oft up/down tir	ne can be fix
				at 0.5 secor	nds. (function	selection swite	ch SW7 off)				·	
Feed	dback cont	rol method		AC CLR (Ty	pes with cont	trol method A)			Г	For types with	n control meth	nds B C D a
	(Phase control method only)			AC CLR (Types with control method A) For types with control methods B, C, D, and E, priority is given to the AC CLR function.								
				AC AVR + AC CLR (Types with control method C) AC AWR + AC CLR (Types with control method D) AC AWR + AC CLR (Types with control method D)								
					DC feedback control + AC CLR (Types with control method E) selection switch SW6 is turned off. When CLR setting is 100%, it uses its built-in CT to detect a load current of about 90% or more of the rated current.							
		sh current suppression (Note 4	4)									
(Cyc	cle control r	method only)		Reduces it by switching the phase angle (Applicable only to types with control method A. Function selection switch SW6 off)								
	1			,				le el				
	J memory e					ted at startup;						
Powe	ver supply e	error				r supply freque						
Error detection and protection wood protection about protection of the protection about protection about protection		NI-t- T)	Oin als inhead	 (2) Detects sudden control power supply frequency change of ±2.5 Hz or more Detects power supply undervoltage (100 V series: 85 V or less; 200 V series: 165 V or less; 400 V series: 315 V or less 								
	lervoltage (Note 5)	Single-phase									: 315 V or less
u			Three-phase			dervoltage (20						
을 Over	rvoltage (N	lote 5)	Single-phase	Detects power supply overvoltage (100 V series: 140 V or more; 200 V series: 265 V or more; 400 V series: 535 V or								
lec				more)								
5 			Three-phase	Detects power supply overvoltage (200 V series: 265 V or more; 400 V series: 535 V or more)								
2 Over	rcurrent			Detects currents of about 120% or more of rated current using built-in CT (Supports types with control methods A, B, C,								
				E, and P)								
۳ <u> </u>	n fuse blown			Lises huilt-in								
Main	n fuse blow					fuse to stop o						
Main		nection (Note 6)								n threshold (S	upports types	with control
Main				Uses built-ir		t when load cu				n threshold (S	upports types	with control
Main Heat		nection (Note 6)		Uses built-ir methods A, Detects load	CT to detect B, C, D, and d current exce	t when load cu E) eeding the CLI	rrent becom	es less than di	sconnectio		supports types duce it to within	
Main Heat	ter disconn	nection (Note 6)		Uses built-ir methods A, Detects load	CT to detect B, C, D, and d current exce	t when load cu E)	rrent becom	es less than di	sconnectio			
Main Heat Curre	ter disconn	nection (Note 6)		Uses built-ir methods A, Detects load values (Sup	CT to detect B, C, D, and current exce ports types w	t when load cu E) eeding the CLI vith control me	R setting valu R setting valu	es less than di les and switch , D, E, and P)	sconnection	se angle to rec		n the CLR set
Main Heat Curre	ter disconn	nection (Note 6)		Uses built-ir methods A, Detects load values (Sup Detects sho	CT to detect B, C, D, and d current exce ports types w rt-circuit of th	t when load cu E) eeding the CLI vith control me	R setting valu thods A, B, C uilt-in CT (Su	es less than di les and switch , D, E, and P) ipports types v	sconnection es the phas vith control	se angle to rec	duce it to within	n the CLR set
Main Heat Curre Thyri	ter disconn	nection (Note 6) stection rmality		Uses built-in methods A, Detects load values (Sup Detects sho pulse. Howe	CT to detect B, C, D, and d current exce ports types w rt-circuit of th	t when load cu E) eeding the CLI vith control me yristor using b e cases where	R setting valu thods A, B, C uilt-in CT (Su	es less than di les and switch , D, E, and P) ipports types v	sconnection es the phas vith control	se angle to rec	duce it to within	n the CLR set
Main Heat Curre Thyri Over	iter disconn rent limit de ristor abnor erheating er	nection (Note 6) stection rmality		Uses built-ir methods A, Detects load values (Sup Detects sho pulse. Howe Detects usir	n CT to detect B, C, D, and d current exce ports types w rt-circuit of th ever, there are ng temperature	t when load cu E) eeding the CLI vith control me yristor using b e cases where	R setting valu thods A, B, C uilt-in CT (Su it is not pose	es less than di les and switch , D, E, and P) ipports types v sible to stop ou	sconnection es the phas vith control utput.	se angle to rec	duce it to within	n the CLR set
Main Heat Curre Thyri Over Com	ter disconn rent limit de ristor abnor rheating er nmunicatior	nection (Note 6) stection rmality ror n error (Optional)		Uses built-ir methods A, Detects load values (Sup Detects sho pulse. Howe Detects usir Detects tran	CT to detect B, C, D, and d current exce ports types w rt-circuit of th ever, there are ng temperatur ismission error	t when load cu E) eeding the CLI vith control me yristor using b e cases where re sensor ors between A	R setting valu thods A, B, C uilt-in CT (Su it is not poss	es less than di les and switch , D, E, and P) ipports types v sible to stop ou	sconnection es the phas vith control utput.	se angle to rec	duce it to within	n the CLR set
Main Heat Curre Thyri Com Cool	ter disconn rent limit de ristor abnor rheating er nmunicatior ling fan life	ection (Note 6) stection mality ror n error (Optional) i (air-cooled products only)		Uses built-ir methods A, Detects load values (Sup Detects sho pulse. Howe Detects usir Detects tran Detects 70%	n CT to detect B, C, D, and d current exce ports types w rt-circuit of th ever, there are ng temperatur ismission error 6 or less of st	t when load cu E) eeding the CLI vith control me yristor using b e cases where re sensor prs between A ready-state rot	R setting valu thods A, B, C uilt-in CT (Su it is not poss PRs during p ation speed	es less than di les and switch c, D, E, and P) upports types v sible to stop ou arallel operation	sconnection es the phas vith control utput.	se angle to rec	duce it to within	n the CLR set
Main Heat Curre Thyri Com Cool	ter disconn rent limit de ristor abnor rheating er nmunicatior ling fan life	nection (Note 6) stection rmality ror n error (Optional)		Uses built-ir methods A, Detects load values (Sup Detects sho pulse. Howe Detects usir Detects tran Detects 70% (1) Detects	n CT to detect B, C, D, and d current exce ports types w rt-circuit of th ever, there are ng temperatur ismission error 6 or less of st disconnection	t when load cc. E) aeding the CLI vith control me yristor using b e cases where re sensor ors between A teady-state rot n of current an	R setting valu thods A, B, C uilt-in CT (Su it is not poss PRs during p ation speed d voltage set	es less than di les and switch r, D, E, and P) upports types v sible to stop ou arallel operation ting signals	sconnection es the phas vith control utput.	se angle to rec	duce it to within	n the CLR set
Main Heat Curre Thyri Over Com Cool Exter	ter disconn rent limit de ristor abnor rheating er nmunicatior ning fan life ernal setting	ection (Note 6) stection mality ror n error (Optional) i (air-cooled products only)		Uses built-ir methods A, Detects load values (Sup Detects sho pulse. Howe Detects usir Detects tran Detects 70% (1) Detects (2) Detects	n CT to detec B, C, D, and d current exce ports types w rt-circuit of th wer, there are go temperatur ismission error 6 or less of st disconnection	t when load cc. E) aeding the CLI ith control me yristor using b e cases where re sensor ors between A teady-state rot n of current an n of manual am	R setting valu thods A, B, C uilt-in CT (Su it is not poss PRs during p ation speed d voltage set	es less than di les and switch r, D, E, and P) upports types v sible to stop ou arallel operation ting signals	sconnection es the phas vith control utput.	se angle to rec	duce it to within	n the CLR set
Main Heat Curre Thyri Over Com Cool Exter	ter disconn rent limit de ristor abnor rheating er nmunicatior ling fan life ernal setting d error	ection (Note 6) stection mality ror n error (Optional) i (air-cooled products only)		Uses built-in methods A, Detects load values (Sup Detects sho pulse. Howe Detects usin Detects ran Detects 70° (1) Detects (2) Detects (1) Detects	n CT to detect B, C, D, and d current exca ports types w rt-circuit of th aver, there arc ing temperatur ismission error 6 or less of st disconnection when load is	t when load cu E) eeding the CLI with control me yristor using b e cases where re sensor ors between A eedy-state rot n of current an of manual ar open	R setting valuations of the setting valuation of the setting valuation of the setting valuation of the setting present of the setting setting the setting setting setting the setting	es less than di les and switch r, D, E, and P) upports types v sible to stop ou arallel operation ting signals	sconnection es the phas vith control utput.	se angle to rec	duce it to within	n the CLR set
Main Heat Curre Thyri Over Com Cool Exter Load (Only	ter disconn rent limit de ristor abnor munication ding fan life ernal setting d error ly types wit	ection (Note 6) stection mality ror n error (Optional) (air-cooled products only) g input disconnection (Note 7) h control method P)		Uses built-in methods A, Detects load values (Sup Detects sho pulse. Howe Detects usin Detects tran Detects Tan Detects 70% (1) Detects (2) Detects (2) If the load	n CT to detect B, C, D, and d current excer- ports types w rt-circuit of th ever, there are ng temperatur ismission error 6 or less of st disconnection when load is d current is d	t when load cc. E) aeding the CLI with control me yristor using b a cases where re sensor prs between A teady-state rot n of current an open lelayed by 30°	R setting valu hods A, B, C uilt-in CT (Su it is not pose PRs during p ation speed d voltage set d gradient se or more	es less than di les and switch r, D, E, and P) piports types sible to stop or arallel operation ting signals ttters	sconnection es the phase with control utput.	e angle to recommethods A, B	duce it to within	n the CLR set
Main Heat Curre Thyri Over Com Cool Exter Load (Only Anale	ter disconn rent limit de ristor abnor rheating er nmunicatior ling fan life grrnal setting d error ly types witt log output d	ection (Note 6) stection mality ror n error (Optional) (air-cooled products only) g input disconnection (Note 7) h control method P) current error (Optional)		Uses built-ir methods A, Detects load values (Sup Detects sho pulse. Howe Detects usin Detects ran Detects 70% (1) Detects (2) Detects (2) If the load Detects when	n CT to detect B, C, D, and d current exceptor ports types w int-circuit of th ever, there are ing temperature ismission error 6 or less of st disconnection when load is id current is d in the allowable	t when load cc. E) aeding the CLI with control me yristor using b e cases where re sensor pros between A ieady-state rot n of current an n of manual am open lelayed by 30° e load resistance	R setting valu hods A, B, C uilt-in CT (St it is not pose PRs during p ation speed d voltage set d gradient set or more the scceeded	es less than di les and switch , D, E, and P) pports types s lible to stop of arallel operation ting signals atters	sconnection es the phase vith control ttput.	e angle to recommethods A, B	duce it to within	n the CLR set
Main Heat Curre Thyri Over Com Cool Exter Load (Only Anale Alarr	ter disconn rent limit de ristor abnor rheating er nmunicatior ling fan life rnal setting d error ly types wit log output d m contact of	ection (Note 6) stection rmality ror n error (Optional) (air-cooled products only) g input disconnection (Note 7) h control method P) current error (Optional) putput	Single phase	Uses built-in methods A, Detects load values (Sup Detects sho pulse. Howe Detects usin Detects tran Detects 70% (1) Detects (2) Detects (2) Detects (2) If the load Detects whe Relay conta	CT to detec B, C, D, and d current exce ports types w rt-circuit of th aver, there are g temperatuu ismission error 6 or less of st disconnectior disconnectior when load is n the allowable ct: Major failu	t when load cu E) seding the CLI with control me tryristor using b e cases where re sensor ors between A iceady-state rot n of current an n of manual ar open lelayed by 30° e load resistanc are + minor fail	A setting valu thods A, B, C uilt-in CT (Su it is not pose PRs during p ation speed d voltage set d gradient se or more be is exceeded ure [1a + 1a	es less than di lies and switch , D, E, and P) pipports types v sible to stop or arallel operatii ting signals tters d when using c contact, 250 N	sconnection es the phase vith control ttput.	se angle to recommethods A, B	duce it to within i, C, D, E, and output boards	n the CLR set
Main Heat Curre Thyri Com Cool Exter Load (Only Anale Alarr	ter disconn rent limit de ristor abnor rheating er nmunicatior ling fan life grrnal setting d error ly types witt log output d	ection (Note 6) stection rmality ror n error (Optional) (air-cooled products only) g input disconnection (Note 7) h control method P) current error (Optional) putput	Single-phase	Uses built-in methods A, Detects load values (Sup Detects sho pulse. Howe Detects usin Detects usin Detects ro? (1) Detects (2) Detects (2) Detects (2) If the load Detects whe Relay conta -5 to +50°C (CT to detec B, C, D, and d current exce ports types w rt-circuit of th aver, there are g temperatur ismission error 6 or less of st disconnectior disconnectior when load is d current is d d current is d r the allowable ct: Major failu reduces load of	t when load cu E) seding the CLI with control me yristor using b e cases where re sensor ors between A teady-state rot n of current an n of manual an open lelayed by 30° e load resistance ure + minor fail current to the ra	A setting value thods A, B, C uilt-in CT (Su it is not poss PRs during p ation speed d voltage set d gradient set or more be is exceeded ure [1a + 1a ted current va	es less than di les and switch , D, E, and P) pipports types i sible to stop or arallel operation ting signals tters d when using ci contact, 250 V ue when the te	sconnection es the phase vith control ttput.	se angle to recommethods A, B s from analog obetween +50°0	duce it to within i, C, D, E, and output boards C and +55°C)	n the CLR set
Main Heat Curre Thyri Com Cool Exter Load (Only Anale Alarr	ter disconn rent limit de ristor abnor rheating er nmunicatior ding fan life grnal setting d error ly types witt log output o m contact o pient tempe	ection (Note 6) stection rmality ror n error (Optional) (air-cooled products only) g input disconnection (Note 7) h control method P) current error (Optional) output brature	Single-phase	Uses built-ir methods A, Detects load values (Sup Detects sho pulse. Howe Detects usir Detects usir Detects 109 (1) Detects (2) Detects (2) Detects (2) Detects (2) If the loa Detects whe Relay conta -5 to +50°C (-5 to +40°C	CT to detect B, C, D, and d current exce ports types w rt-circuit of th aver, there are g temperatur ismission error 6 or less of st disconnectior when load is d current is d d current is d current is d curent is d current is d current is	t when load cu E) seding the CLI with control me tryristor using b e cases where re sensor ors between A iceady-state rot n of current an n of manual ar open lelayed by 30° e load resistanc are + minor fail	A setting value thods A, B, C uilt-in CT (Su it is not poss PRs during p ation speed d voltage set d gradient set or more be is exceeded ure [1a + 1a ted current va	es less than di les and switch , D, E, and P) pipports types i sible to stop or arallel operation ting signals tters d when using ci contact, 250 V ue when the te	sconnection es the phase vith control ttput.	se angle to recommethods A, B s from analog obetween +50°0	duce it to within i, C, D, E, and output boards C and +55°C)	n the CLR set
Main Heat Curre Thyri Over Com Cool Exter Load (Only Anale Alarr	ter disconn rent limit de ristor abnor rheating er nmunicatior ling fan life rnal setting d error ly types wit log output d m contact of	ection (Note 6) stection rmality ror n error (Optional) (air-cooled products only) g input disconnection (Note 7) h control method P) current error (Optional) output brature		Uses built-in methods A, Detects load values (Sup Detects sho pulse. Howe Detects usin Detects usin Detects ro? (1) Detects (2) Detects (2) Detects (2) If the load Detects whe Relay conta -5 to +50°C (CT to detect B, C, D, and d current exce ports types w rt-circuit of th aver, there are g temperatur ismission error 6 or less of st disconnectior when load is d current is d d current is d current is d curent is d current is d current is	t when load cu E) seding the CLI with control me yristor using b e cases where re sensor ors between A teady-state rot n of current an n of manual an open lelayed by 30° e load resistance ure + minor fail current to the ra	A setting value thods A, B, C uilt-in CT (Su it is not poss PRs during p ation speed d voltage set d gradient set or more be is exceeded ure [1a + 1a ted current va	es less than di les and switch , D, E, and P) pipports types i sible to stop or arallel operation ting signals tters d when using ci contact, 250 V ue when the te	sconnection es the phase vith control ttput.	se angle to recommethods A, B s from analog obetween +50°0	duce it to within i, C, D, E, and output boards C and +55°C)	n the CLR set
Main Heat Curre Thyri Com Cool Exter Load (Only Anale Alarr	ter disconn rent limit de ristor abnor rheating er nmunicatior ding fan life grnal setting d error ly types witt log output o m contact o pient tempe	ection (Note 6) stection rmality ror n error (Optional) (air-cooled products only) g input disconnection (Note 7) h control method P) current error (Optional) putput irature rature		Uses built-in methods A, Detects load values (Sup Detects sho pulse. Howe Detects usin Detects tran (1) Detects (2) Detects (2) If the load Detects whe Relay conta -5 to +50°C (-5 to +60°C	CT to detect B, C, D, and d current exce ports types w rt-circuit of th aver, there are g temperatur ismission error 6 or less of st disconnectior when load is d current is d d current is d current is d curent is d current is d current is	t when load cu E) beding the CLI with control me yristor using b e cases where re sensor ors between A teady-state rot n of current an n of manual an open lelayed by 30° e load resistance ure + minor fail surrent to the ra- tive to rated cu	A setting value thods A, B, C uilt-in CT (Su it is not poss PRs during p ation speed d voltage set d gradient set or more be is exceeded ure [1a + 1a ted current va	es less than di les and switch , D, E, and P) pipports types i sible to stop or arallel operation ting signals tters d when using ci contact, 250 V ue when the te	sconnection es the phase vith control ttput.	se angle to recommethods A, B s from analog obetween +50°0	duce it to within i, C, D, E, and output boards C and +55°C)	n the CLR set
Main Heat Curre Thyri Over Com Cool Exter Load (Only Anale Alarr	ter disconn rent limit de ristor abnor rheating er mmunicatior ding fan life ernal setting d error ly types wit log output o m contact o bient tempe rage tempe bient humid	ection (Note 6) stection rmality ror n error (Optional) (air-cooled products only) g input disconnection (Note 7) h control method P) current error (Optional) putput irature rature		Uses built-ir methods A, Detects load values (Sup Detects sho pulse. Howe Detects usin Detects tran Detects 70° (1) Detects (2) Detects (2) If the loa Detects whe Relay conta -5 to +50°C (-50 to +60°C	n CT to detect B, C, D, and d current excer ports types w rt-circuit of th aver, there are ng temperatur ismission error 6 or less of st disconnection disconnection when load is d current is di n the allowablic ct: Major failu reduces load of (reduces relation C RH (no condet)	t when load cc. E) eeding the CLI ith control me yristor using b e cases where re sensor ors between A teady-state rot n of current an n of current an n of manual ar open lelayed by 30° e load resistance ure + minor fail uurrent to the ra tive to rated cu nsation)	R setting valu thods A, B, C uilt-in CT (St it is not poss PRs during p ation speed d voltage set d gradient se or more ce is exceeded lure [1a + 1a ted current va urrent value v	es less than di les and switch , D, E, and P) pipports types v sible to stop ou arallel operation ting signals titers d when using ci contact, 250 V ue when the te when the temp	sconnection es the phase vith control trput.	s from analog of between +50°C	duce it to within i, C, D, E, and output boards C and +55°C)	n the CLR set
Main Heat Curre Thyri Over Com Cool Exter Load (Only Anale Alarr Amb	ter disconn rent limit de ristor abnor rheating er mmunicatior ding fan life ernal setting d error ly types wit log output o m contact o bient tempe rage tempe bient humid	ection (Note 6) stection rmality ror n error (Optional) (air-cooled products only) g input disconnection (Note 7) h control method P) current error (Optional) putput irature rature		Uses built-ir methods A, Detects load values (Sup Detects sho pulse. Howe Detects usin Detects tran Detects tran Detects 70% (1) Detects (2) Detects (2) If the load Detects when Relay conta -5 to +50°C -50 to +60°C 30 to 90% F No corrosive	n CT to detect B, C, D, and d current excer ports types w rt-circuit of th aver, there are ng temperatur ismission error 6 or less of st disconnection disconnection when load is d current is di n the allowablic ct: Major failu reduces load of (reduces relation C RH (no condet)	t when load cc. E) aeding the CLL with control me yristor using b a cases where re sensor ors between A teady-state rot n of current an open lelayed by 30° a load resistance re + minor fail current to the ra tive to rated co msation) , substances a	R setting valu thods A, B, C uilt-in CT (St it is not poss PRs during p ation speed d voltage set d gradient se or more ce is exceeded lure [1a + 1a ted current va urrent value v	es less than di les and switch , D, E, and P) pipports types v sible to stop ou arallel operation ting signals titers d when using ci contact, 250 V ue when the te when the temp	sconnection es the phase vith control trput.	s from analog of between +50°C	duce it to within , C, D, E, and , C, D, E, and output boards <u>C and +55°C</u>) and +55°C)	n the CLR set
Main Heat Curre Thyri Over Cool Exter Anale Alarr Anale Alarr Store Store Othe	ter disconn rent limit de ristor abnor rheating er nmunication ling fan life rmal setting d error ly types wit log output d m contact o oient tempe age tempe oient humid ers	ection (Note 6) stection rmality ror n error (Optional) (air-cooled products only) g input disconnection (Note 7) h control method P) current error (Optional) putput irature rature		Uses built-ir methods A, Detects load values (Sup Detects sho pulse. Howe Detects usin Detects train Detects ro? (1) Detects (2) Detects (2) Detects (2) Detects (2) Detects (2) If the load Detects whee Relay conta -5 to +50°C (-5 to +40°C -20 to +60°C 30 to 90% F No corrosive altitude of 10	CT to detect B, C, D, and d current excet ports types w rt-circuit of th aver, there are g temperature ismission error disconnection disconnection disconnection disconnection disconnection when load is d current is d in the allowable ct: Major failu reduces load d (reduces relation C att (no conde a gases, dust 000 m or less	t when load cc. E) aeding the CLL with control me yristor using b a cases where re sensor ors between A teady-state rot n of current an open lelayed by 30° a load resistance re + minor fail current to the ra tive to rated co msation) , substances a	A setting value thods A, B, C uilt-in CT (Su it is not poss PRs during p ation speed d voltage set d gradient set or more be is exceeded ure [1a + 1a ted current value v and actions th	es less than di les and switch , D, E, and P) pipports types i sible to stop or arallel operation ting signals tters d when using ci contact, 250 V ue when the terport that promote in	sconnection es the phase vith control ttput.	se angle to recommethods A, B s from analog of between +50°C etween +40°C	duce it to within , C, D, E, and , C, D, E, and output boards <u>C and +55°C</u>) and +55°C)	n the CLR sett

(Note 1) The rated voltage always operates as either 110 V or 220 V. For use at 230 V or 240 V, adjust the maximum output voltage at the power supply voltage compensation setting (PVC setting).
 (Note 2) When cycle control is used, connecting a transformer such as a VT to the output side may cause the bias magnetism phenomenon. Use after disconnecting transformers such as VTs. "Transformer primary control via cycle control is used, connecting a transformer such as a VT to the output side may cause the bias magnetism phenomenon. Use after disconnecting transformers such as VTs. "Transformer primary control via cycle control is used, connecting a transformer such as a VT to the output side may cause the bias magnetism phenomenon. Use after disconnecting transformers such as VTs. "Transformer primary control via cycle control is valid only for types with control method P.
 (Note 3) For types with control methods B, C, D, and E, even if the soft start and soft up/down time are set to be short, there may be cases when the time may not be shortened because priority is given to the response speed of feedback control. The time can be set longer.
 (Note 4) Automatic inrush current suppression suppresses the occurrence of overcurrent through control in combination with phase control. If a transformer such as VT is connected to the output side, please use it after disconnecting transformers such as VTs because cycle control could cause the bias magnetism phenomenon.
 (Note 5) Control power supply voltage is automatically detected when power is turned on. Therefore, if the power supply voltage is slowly increased or decreased, or if a 110 V series power supply is switched with a 220 V series power supply, an "overvoltage" alarm will be detected.
 (Note 6) For cycle control (types with control method A), the alarm is "load open detection".
 (Note 7) It does not operate for the voltage signal 0 to 5 V DC setting (function selection switch SW



Rating, type (= product code)

hase number	Input voltage [V]	Rated current [A]	Rated load capacity [kVA] (Note 1)	Built-in fast-acting fuse (Note 2)	Type (= product code)	
ingle-phase	100 to 240 V	20	2-4.8	CR6L-30G/UL	RPVE2020-T	
					RPVE2020-A	
		45	4.5-10.8	CR6L-75G/UL	RPVE2045-T	
					RPVE2045-A	
		60	6-14.4	CR6L-100G/UL	RPVE2060-T	
					RPVE2060-A	
		100	10-24	CR6L-150G/UL	RPVE2100-T	
					RPVE2100-A	
		150	15-36	CR6L-200G/UL	RPVE2150-T	
					RPVE2150-A	
		250	25-60	6, 9URD30TTF0350	RPVE2250-T	
					RPVE2250-A	
		350	35-84	6, 9URD31TTF0500	RPVE2350-T	
					RPVE2350-A	
		450	45-108	6, 9URD31TTF0630	RPVE2450-T	
					RPVE2450-A	
		600	60-144	CS5F-800/UL	RPVE2600-T	
					RPVE2600-A	
	380 to 480 V	20	7.6-9.6	CR6L-30G/UL	RPVE4020-T	
					RPVE4020-A	
		45	17.1-21.6	CR6L-75G/UL	RPVE4045-T	
					RPVE4045-A	
		60	22.8-28.8	CR6L-100G/UL	RPVE4060-T	
					RPVE4060-A	
		100	38-48	CR6L-150G/UL	RPVE4100-T	
					RPVE4100-A	
		150	57-72	CR6L-200G/UL	RPVE4150-T	
					RPVE4150-A	
		250	95-120	6, 9URD30TTF0350	RPVE4250-T	
		200	00.20	0,0012001110000	RPVE4250-A	
		350	133-168	6, 9URD31TTF0500	RPVE4350-T	
		000	100 100	0,001201110000	RPVE4350-A	
		450	171-216	6, 9URD31TTF0630	RPVE4450-T	
		-50	171210	0,001201110000	RPVE4450-A	
		600	228-288	CS5F-800/UL	RPVE4600-T	
		000	220-200	0001-000/0E	RPVE4600-A	
ree-phase	200 to 240 V	20	6.9-8.3	CR6L-30G/UL	RPVW2020-T	
ree-priase	200 10 240 V	20	0.3-0.5	ONDE-SOCIOE	RPVW2020-A	
		45	15.6-18.7	CR6L-75G/UL	RPVW2020-A	
		45	13.0-10.7	CHOE-7 SC/DE	RPVW2045-1	
		60	20.8-24.9	CR6L-100G/UL	RPVW2045-A	
		60	20.8-24.9	CROL-100G/UL		
		100	04.0.44.0		RPVW2060-A	
		100	34.6-41.6	CR6L-150G/UL	RPVW2100-T	
		450	50.0.00.4		RPVW2100-A	
		150	52.0-62.4	CR6L-200G/UL	RPVW2150-T	
		050	00.0.400.0		RPVW2150-A	
		250	86.6-103.9	6, 9URD30TTF0350	RPVW2250-T	
		450			RPVW2250-A	
		450	155.9-187.1	6, 9URD31TTF0630	RPVW2450-T	
			007.0.0/5.		RPVW2450-A	
		600	207.8-249.4	CS5F-800/UL	RPVW2600-T	
					RPVW2600-A	
	380 to 480 V	20	13.2-15.2	CR6L-30G/UL	RPVW4020-T	
					RPVW4020-A	
		45	29.6-34.3	CR6L-75G/UL	RPVW4045-T	
					RPVW4045-A	
		60	39.5-45.7	CR6L-100G/UL	RPVW4060-T	
					RPVW4060-A	
		100	65.8-76.2	CR6L-150G/UL	RPVW4100-T	
					RPVW4100-A	
		150	98.7-114.3	CR6L-200G/UL	RPVW4150-T	
					RPVW4150-A	
		250	164.5-190.5	6, 9URD30TTF0350	RPVW4250-T	
					RPVW4250-A	
		450	296.2-342.9	6, 9URD31TTF0630	RPVW4450-T	
			450			RPVW4450-A
		600	394.9-457.3	CS5F-800/UL	RPVW4600-T	

(Note 1) Rated load capacity is calculated using the following formula. Rated load capacity (single-phase) = Rated input voltage × Output current (Three-phase) = √3 rated input voltage × Output current (Note 2) When replacing only the built-in quick-acting fuse, use the type listed in the table. In the case of a microswitch type (CR6L), replace "G" with "S".

Cooling fan

The average life of the cooling fan is about 40,000 hours. (At an ambient temperature of 50°C and 100% output. 600 A products have an average life of about 23,000 hours.)

Replace with a new product as soon as required in consideration of this service life.

An alarm will trigger when the cooling fan reaches the end of its service life. (Green or yellow LED blinking)

Cooling fan, order type

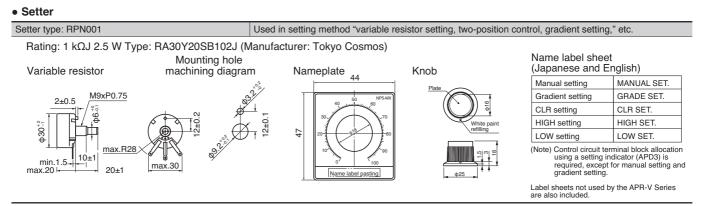
Single-phase

APR rated current	Cooling fan, order type	Required qty.
150 A	RPVE150 fan motor	1 pc. / 1 unit
250 A	RPVE250 fan motor	
350 A	RPVE350 fan motor	
450 A	RPVE450 fan motor	
600 A	RPVE600 fan motor	

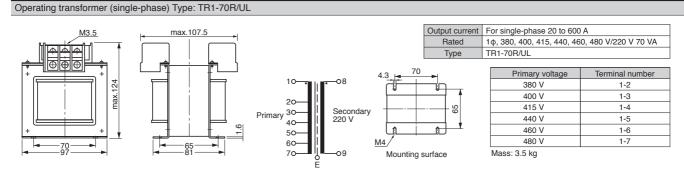
	Three-phase						
	APR rated current	Cooling fan, order type	Required qty.				
150 A		RPVW150 fan motor	2 pcs. / 1 unit				
	250 A	RPVW250 fan motor					
	450 A	RPVW450 fan motor					
	600 A	RPVW600 fan motor					

(Note) Please contact us for fan guard orders of cooling fans.

Other optional items (sold separately)



• Transformer for control power supply (UL certified products)



General-purpose low-voltage operating transformers can also be used. (Not UL compliant) Catalog No. HS192 Ex. CU1F-050-A4020

• Mounting bracket for external cooling installation

For single-phase (RPV004-E

Туре	Content		
RPV004-E02	For RPVE 020-		
RPV004-E06	For RPVE_045, RPVE_060		
RPV004-E10 For RPVE 100-			
RPV004-E15	For RPVE 150-		
RPV004-E25	For RPVE 250-		
RPV004-E45 For RPVE 350- , RPVE 450-			
RPV004-E60	For RPVE 600-		

For three-phase (RPV004-W

Туре	Content		
RPV004-W02	For RPVW_020-		
RPV004-W06	For RPVW_045, RPNW_060		
RPV004-W10 For RPVW 100-			
RPV004-W15 For RPVW 150-			
RPV004-W25	04-W25 For RPVW 250-		
RPV004-W45 For RPVW_450-			
RPV004-W60	For RPVW_600-		



• Finger guard

For single-phase (RPV005-E

0 1	·/
Туре	Content
RPV005-E02	For RPVE 020-
RPV005-E06	For RPVE_045, RPVE_060
RPV005-E10	For RPVE 100-
RPV005-E15	For RPVE 150-
RPV005-E25	For RPVE 250-
RPV005-E45	For RPVE_350, RPVE_450
RPV005-E60	For RPVE 600-

• CT and VT for feedback control

Product name	Туре		Rated primary input	Rated secondary output, etc.
СТ	CT-5S	to	20 A, 45 A, 60 A 100 A, 150 A, 250 A 350 A, 450 A, 600 A	Rated secondary: 0.1 A Rated load: 5 VA Accuracy class: Class 1
VT	PT-5S	100 V/10 V	100, 110 V	Rated secondary: 10 V
	PT-5S	200 V/10 V	200, 220 V	Rated load: 5 VA
	PT-5S	230 V/10 V	230, 254 V	Accuracy class: Class 1
	PT-5S	380 V/10 V	380 V	
	PT-5S	400 V/10 V	400, 440 V	
	PT-5S	415 V/10 V	415 V	
	PT-5S	420 V/10 V	420, 460 V	
	PT-5S	440 V/10 V	440, 480 V	

(Note) CT-5S primary through-hole turns: 5 turns for 20 A, 3 turns for 45 A, 2 turns for 60 A, and 1 turn for others.

The primary voltage of PT-5S is a 2-tap input except for 380 V and 415 V.

Main circuit terminal cover

For three-phase (RPV006-W

Туре	Content
RPV006-W02	For RPVW_020-
RPV006-W06	For RPVW_045, RPVW_060
RPV006-W10	For RPVW 100-
RPV006-W15	For RPVW 150-
RPV006-W25	For RPVW 250-
RPV006-W45	For RPVW 450-
RPV006-W60	For RPVW_600-

(Note) Single-phase has no main circuit terminal cover because it is already supported as standard.

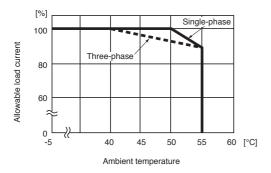
Standard.

Important notes in selecting products

Allowable load current - ambient temperature characteristics

The rated current value for single-phase is based on an ambient temperature of 50° C (40° C for three-phase).

If the ambient temperature is higher than this, use it after reducing the load current as shown below.



For three-phase (RPV005-W)

Туре	Content			
RPV005-W02	For RPVW_020-			
RPV005-W06	For RPVW_045, RPVW_060			
RPV005-W10 For RPVW_100				
RPV005-W15	For RPVW 150-			
RPV005-W25 For RPVW_250				
RPV005-W45 For RPVW_450				
RPV005-W60	For RPVW_600-			

• Setting indicator, remote control connection cable

Product name	Туре	Name	Specifications
Setting indicator	APD3	-	-
Cable	RPN002-1	Remote control connection cable	Length: 1 m
	RPN002-3	Remote control connection cable	Length: 3 m
	RPN002-5	Remote control connection cable	Length: 5 m

• Transformer primary control

- (1) The wiring of a three-phase transformer should be the $\Delta/{\rm L}$ method, not ${\rm L}/{\rm L}.$
- (2) If there is a risk of the transformer becoming unloaded, connect a resistor in parallel with the primary winding so that about 0.5 A (at rated voltage) flows through it.
- (3) Allow enough margin for magnetic flux density to prevent bias magnetism.

(1.0 to 1.2 T or less)

- (4) Do not use in cycle control except for single-phase P types.
- (5) In the case of three-phase, the load imbalance should be 10% or less.

• Important notes for power cycle life expectancy

If RUN and STOP are repeated at short-period cycles (for example, 30-minute RUN and 30-minute STOP), a large difference in temperature occurs in the thyristor element, significantly shortening its life expectancy due to thermal fatigue.

For such applications, select a capacity with a load current less than 80% of the rated current.

Control function

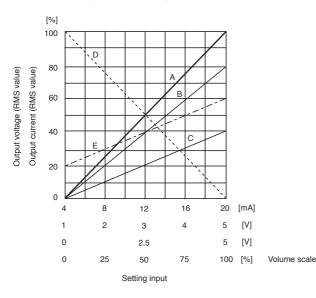
• Input-output characteristic

• Setting signal, gradient setting, base load setting - output characteristics (for resistive load, operating principle characteristics) The figure below shows characteristic A when the base load setting and gradient setting are not used.

Output varies linearly with various setting inputs.

By using the gradient setting and base load setting (optional) together, the input-output characteristics can be changed as desired, as shown in the example in the graph below.

It is common to phase control, cycle control, or each feedback control method.



The left graph shows examples of base load setting and gradient setting

Characteristic	Output adjustment range [%]	Base load setting [%]	Gradient setting [%]
А	0 to 100	0	100
В	0 to 80	0	80
С	0 to 40	0	40
D	100 to 0	100	0
E	20 to 60	20	60

*Gradient setting: Set the output value at the maximum setting input in the input-output characteristics

*Base load setting: Set the output value at the minimum setting input in the input-output characteristics

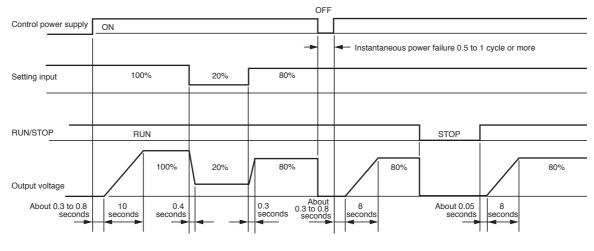
• RUN/STOP (gate on/off) function

Output is turned on by soft start when the RUN-COM terminal is "shorted" and turned off immediately when it is "open" regardless of the setting input. The figure below shows the operation timing. (When a setting indicator is connected or network communication control is used, there are cases where it will not run by only short-circuiting RUN-COM.)

· Soft start and soft up/down function

It activates and gradually changes the output when the control power is turned on, immediately after an instantaneous power failure, when the RUN/STOP signal is turned on, or when the setting signal changes. Therefore, in the case of transformer loads or pure metal heaters or lamp loads, the inrush current can be suppressed by using it in combination with the current limiting function.

The soft start time can be set as desired in the range of 0.5 to 10 seconds or 5 to 100 seconds, respectively. The variable range can be switched by changing DIP switch SW1. The figure below shows the operation timing.



E.g. of RUN/STOP, soft start, and soft up/down time charts

(Soft start setting: 10 seconds; Soft up/down: 0.5 second fixed setting; Control method: T and A types)

(Note)

• The soft start setting time is the time after RUN during which the output increases from 0% to 100%.

· The soft start setting time can be set independently of feedback control.

Soft start setting time and soft up/down setting time can be set as desired by using the setting indicator (APD3).

(Setting time: 0 to 100 seconds)



Setting indicator APD3

Features

The APR-V Series can be operated and configured in a variety of ways.

- \cdot Enables quick selection and display switching using dial operation.
- \cdot Capable of displaying two elements at the same time with data display and multi-indicators.
- \cdot Capable of diagnosing the main unit without a tester by using the input signal check function.
- \cdot Comes with an error detection history display function.
- · Capable of high-precision digital setting.
- Enables customization of functions by changing function codes. (Alarm output assignment and terminal block assignment of internal volume function, etc.)
- \cdot Capable of copying function codes.
- \cdot Complies with revised Chinese RoHS.
- \cdot Not compatible with APD1 or APD2.

Specifications

Item	Specifications			
Туре	APD3			
Protective structure	Panel side: IP40; Back side (mounting surface): IP20			
Location of use	Indoor			
Ambient temperature	-5 to +50°C			
Ambient humidity	30 to 90% RH (no condensation)			
Atmosphere	Locations free from dust, corrosive gases (especially sulfide gas, ammonia gas, etc.), flammable gases, oil mist, vapor, water droplets, and direct sunlight. Locations not subject to salt damage. Ensure no condensation due to sudden temperature changes.			
Altitude	1000 m or less			
Ambient storage temperature	-20 to +60°C			
Ambient storage humidity	30 to 90% RH (no condensation)			
Mounting method	Vertical mounting (wall-mounted)			
Tightening torque for main	unit mounting			
Mounting screws	M3 ×16 2 pcs.			
Tightening torque (±10%)	0.7 N·m (7 kgf·cm)			
Mass	55 g			



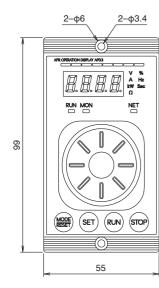
Hardware specifications

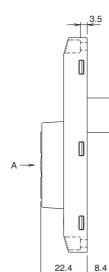
	•		
Item	Specifications		
Remote control connection cable	Straight cable (for 10BASE-T/100BASE-TX) complying with US ANSI/TIA/EIA-568A Category 5 standards		
Maximum communication distance	20 m (not insulated)		
External connection terminal	RJ-45 connector (modular jack connector)		
(Note 1) A remote control connection cable (BPN002-) is required when using the setting			

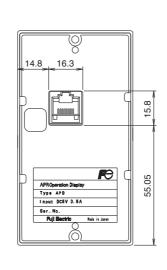
(Note 1) A remote control connection cable (RPN002-□) is required when using the settin indicator.

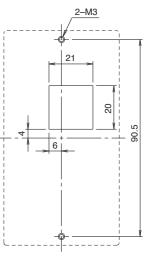
(Note 2) Do not use STP (shielded) cables when using commercial products.

External dimension diagram (unit: mm)





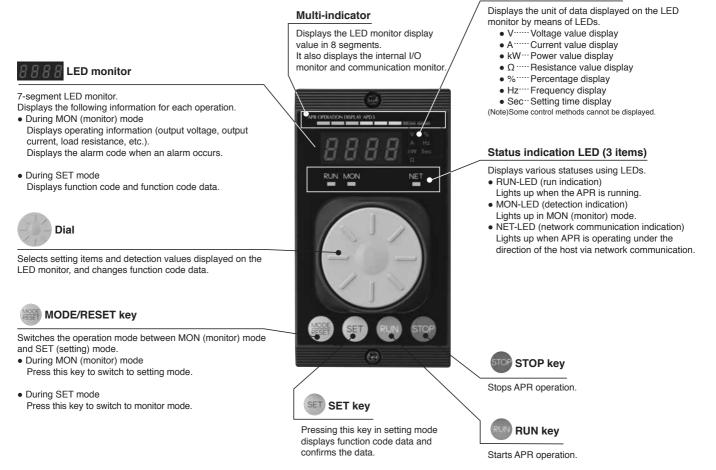




Panel cutout size drawing (Arrow view A)

Unit display LED (7 items)

Setting indicator (APD3) Part names and functions



Display and key operation

		ion mode	e SET mode		MON (monitor) mode			
	play unit		RUN/STOP		Running	RUN/STOP	Running	
Display unit		Function	Displays operation data outputs for fixed display of multi- indicator.		Displays in 8 segments various operation data, internal I/O, and communications monitors.			
olay		Display	ON/Blinking					
Dis	8888	Function	Function code and function code data display When an alarm occurs, it displays an alarm code			Displays output voltage, output current, output power, load resistance value, and output %. When an alarm occurs, it displays an alarm code		
		Display	ON					
		Function	Displays various states	S				
	RUN MON NET	Display	•RUN-LED OFF		•RUN-LED ON	•RUN-LED OFF	•RUN-LED ON	
			•MON-LED OFF			•MON-LED ON		
					n NET is selected using setter			
		Function		ta disp	played on the LED monitor			
	V % A Hr kW Sec Ω	Display	•V-LED Voltage display					
			•A-LED Current display					
			•kW-LED Power display					
			•Ω-LED Resistance value display					
			Percent display					
			•Hz-LED Frequency display					
			Sec-LED Setting time display					
Operating unit		Function	Function code and increase/decrease of function code data		Switching the display r information	node of each type of operation		
era	MODE	Function	Change to MON (mon	Change to MON (monitor) mode		Change to SET mode		
g	RESET				RESET after removing error cause			
	SET	Function	Displays function code data and sets data		-			
	RUN	Function	RUN start		-	RUN start	-	
	STOP	Function	-		RUN/STOP	-	RUN/STOP	

Feedback control

Feedback control accuracy (for resistive loads)

(Ta = 25°C) Control method Variable element Control accuracy (Note) Conditions Current limit regulation (CLR) ±1% FS Power supply voltage fluctuation ±10% Constant load Load fluctuation 4x ±2% FS Constant power supply voltage Automatic current regulation (ACR) ±1% FS Power supply voltage fluctuation ±10% Constant load ±2% FS Constant supply voltage Load fluctuation 4x Automatic voltage regulation (AVR) Power supply voltage fluctuation ±10% ±1% FS Constant load Load fluctuation 4x ±2% FS Constant supply voltage Automatic wattage regulation (AWR) Power supply voltage fluctuation ±10% ±1% FS Constant load Constant supply voltage ±1% FS Load fluctuation 4x

(Note) The control accuracy is a % value of the rated output. The accuracy of DC feedback control depends on the accuracy of the external converter Control accuracy is ±4% FS for 10 times load fluctuation.

The rated voltage or rated current is the upper limit of feedback control.

Waveform control method

The phase control method and cycle control method can be selected by using the DIP switch.

For types with control method A, inrush current automatic suppression cycle control (combined control) can be selected.

Item	Phase control method	Cycle control method	Combined control method (Types with A only) (Note)
Applied load	Applicable to most loads, including resistive and inductive loads (excluding capacitor loads)	Applicable to nichrome and ferrochrome resistance loads (with low temperature coefficient of resistance)	Most resistive loads including pure metal and silicon carbide types
Transformer primary control	Available	Not available (Available for types with control method P)	Not available
Feedback control (AVR, ACR, etc.)	Available	Not available	Not available
Harmonic disturbance	Possible occurrence	No	No (except during suppression)
Flicker occurrence	No	Possible occurrence	Possible occurrence
Responsiveness	Fast	Slow	Slow
Power factor	Bad	Good	Good (except during suppression)

(Note) During current-limiting operation, it temporarily switches to phase control to limit the current flowing to the load to 90% or less of the CLR setting.

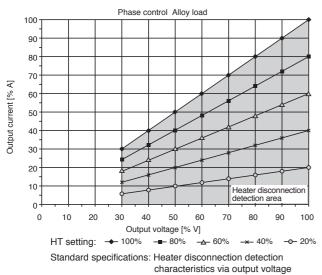
Heater disconnection detection (except for types with control method T)

At the time of standard shipment, it is set to operate only in the standard specification of single-phase. To enable the heater disconnection detection function of the high-performance specification, the setting must be changed using the setting indicator (APD3).

Standard specification (single-phase only)

Detects a disconnection when the load current drops below the current value set by the heater disconnection determination setting volume "HT"

- · Applicable heaters
- Alloy types: 3 or less in parallel
- (Must be of the same material and of the same capacity)
- · Applicable load capacity
- A load that draws 40 to 100% of the APR rated current at 100% APR output voltage.
- · Disconnection determination setting volume "HT"
- When setting less than 3%: Disconnection determination invalid When setting 3% or higher: Disconnection determination valid · Detection range
- Output setting range 30 to 100% (including gradient setting) Output voltage range 30 to 100% V



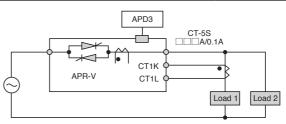
• High-performance specifications (for single-phase)

The load is divided into two, and the currents are compared with each other to detect disconnections.

- Applicable heaters
- Various heaters: 10 (5+5) lines or less in parallel
- (Must be of the same material and of the same capacity) · Applicable load capacity
- A load that draws 50 to 100% of the APR rated current at 100% APR output voltage.
- · Disconnection determination setting
- Settings (number of heaters, determination time, etc.) using setting indicator (APD3)

· Number of parallel lines and detection range

Total	Load 1	Load 2	Detection range
number	Number of parallel lines	Number of parallel lines	(APR output voltage)
2	1	1	30 to 100%
3	1	2	
4	2	2	
5	2	3	
6	3	3	
7	3	4	40 to 100%
8	4	4	
9	4	5	50 to 100%
10	5	5	1



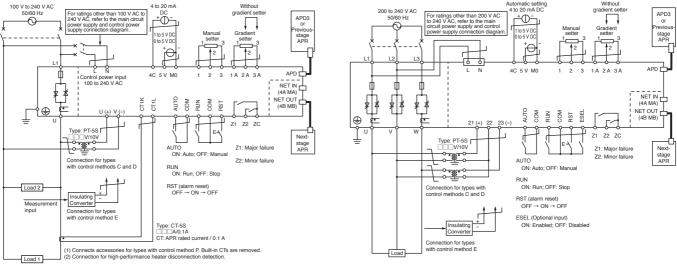
High-performance specifications External connection diagram

· For three-phase types, an external CT connection is not required.

· For three-phase three-wire types, a total of 9 lines can be detected. For three-phase four-wire types, a total of 15 lines can be detected.

External connection

• External connection diagram (In case of single-phase, full connection, with no change in function allocation)

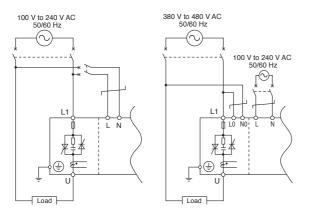


• Control terminal function when setting indicator (APD3) is available (SW8: ON)

You can make function code settings using the setting indicator (APD3) and omit external wiring or change functions using network communication.

Control terminal	Wiring	Remarks
RUN	Required	Operation is not performed when the RUN terminal is OFF. When the RUN terminal is ON, the unit will run or stop when the RUN/STOP key is pressed on the setting indicator (APD3). Operation using the RUN/STOP key on the setting indicator is recorded in non-volatile memory. If the last operation is RUN, the unit will run or stop according to the RUN terminal ON/OFF status. If the last operation is STOP, the unit will not run even if the RUN terminal is ON. *If function code 6.011 is set to OFF, the unit will run or stop according to the RUN terminal ON/OFF status only. *The unit can be started or stopped using network communications if the RUN terminal is ON.
1, 2, 3 1A, 2A, 3A	Select	Settings can be made using the setting indicator (APD3) or network communications, and so wiring is not required. *The functions of the CLR setting can be allocated to an external setter.
AUTO RST	Select	The AUTO terminal can be allocated to HIGH setting/LOW setting switching input for two-position control. The RST terminal cannot be assigned two-position control.
4C, 5V, M0	Select	Control can be performed using network communications if control is made using PLC output.
Z1, Z2, ZC	Select	Alarm codes are displayed on the setting indicator (APD3). Network communications can be used to read alarm codes and check if there are major failures or minor failures.

Main circuit and control power supply connection diagram (single-phase)



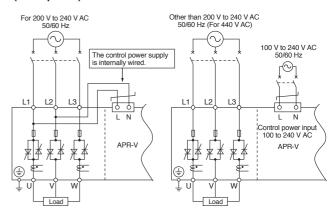
*Be sure to check that the main circuit power supply and the input power supply detection terminals are in phase.

It is not necessary for the L and N terminals of the 400 V system to be in-phase.

Main circuit and control power supply connection diagram (three-phase)

• External connection diagram (In case of three-phase,

full connection, with no change in function allocation)

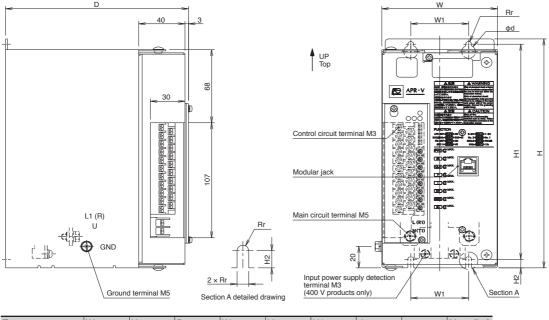


Check that the phase order of the main circuit power supply is L1 \rightarrow L2 \rightarrow L3. If the phase order is not correct, an alarm will occur (red/green LED lights up).



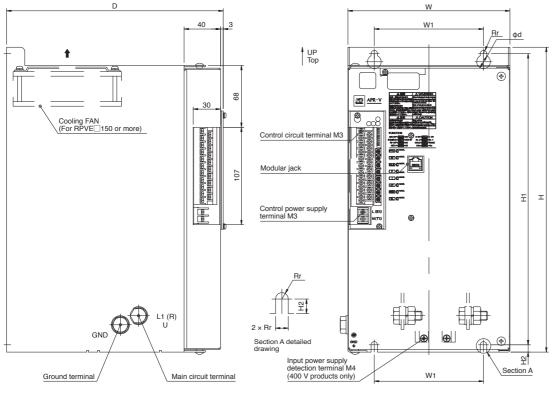
External dimension diagram (single-phase) [unit: mm]

• RPVE 020, RPVE 045, RPVE 060

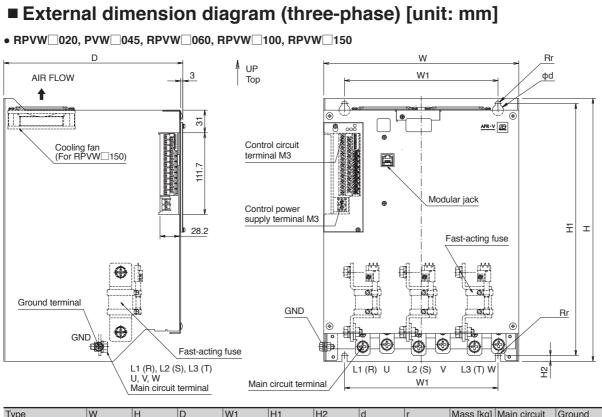


Туре	W	Н	D	W1	H1	H2	d	r	Mass [kg]
RPVE_020	100	213	158	50	200	8	12	2.5	2.6
RPVE 045	114	213	183	60	200	8	12	2.5	3.6
RPVE 060]								

• RPVE 100, RPVE 150, RPVE 250, RPVE 350, RPVE 450, RPVE 600



Туре	W	Н	D	W1	H1	H2	d	r	Mass [kg]	Main circuit terminal	Ground terminal
RPVE 100	144	224	238	90	210	8	14	3	5.3	M8	M8
RPVE_150	160	273	238	90	260	7	14	3	6.4		
RPVE 250	178	335	238	120	320	8	15	3.5	9.0	M10	M10
RPVE 350	200	345	263	150	330	8	15	3.5	10.6]	
RPVE 450											
RPVE 600	207	360	288	157	345	8	15	3.5	13.7	M12	M10

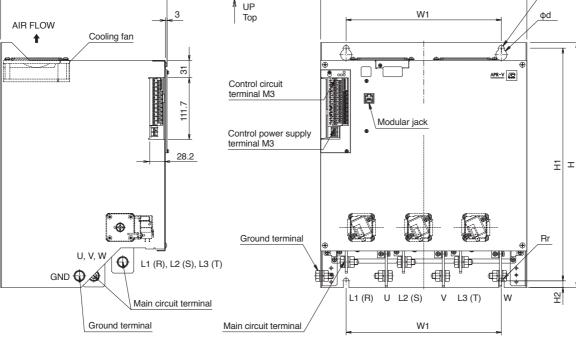


Туре	W	Н	D	W1	H1	H2	d	r			Ground terminal
RPVW 020	230	273	160	200	260	6	14	3	5.0	M5	M5
RPVW_045	238	293	210	205	280	6	14	3	9.5		
RPVW_060											
RPVW 100	267	330	245	210	315	8	15	3.5	11.8	M8	M6
RPVW[]150	267	360	245	210	345	8	15	3.5	13.2		

W

Rr



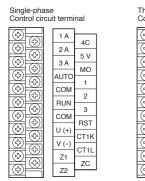


Туре	W	Н	D	W1	H1	H2	d	r			Ground terminal
RPVW_250	267	384	280	200	365	9	20	5	14.3	M10	M8
RPVW 450	372	442	300	280	420	12	20	5	28.1	M10	M10
RPVW_600	372	528	310	280	505	11	24	6	36.8	M12	M10

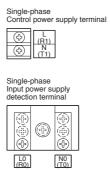
• RPVW 250, RPVW 450, RPVW 600



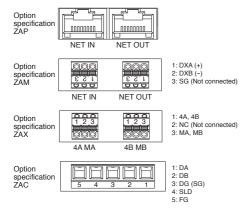
• Terminal block detailed drawing



hree-phase ontrol circuit terminal							
Ð 🔊	1 A	4C					
THE REPORT OF THE PARTY OF THE	2 A						
첫 (원)		5 V					
불위	3 A	мо					
	AUTO	1					
	СОМ						
했순	RUN	2					
¥ (A)	RUN	3					
9	COM						
쥐벨	RST	21 (+)					
꽃(원)	-	22					
y A	ESEL	23 (-)					
Ð	Z1						
<u>s</u> v	Z2	ZC					
	22						



 Communication board connector diagram wiring specifications



• Analog output connector diagram Wiring specifications



1: Current analog output (ZAA) 2: Voltage analog output (ZAB) 3: COM

Note) One of the signal outputs is either a current analog signal or a voltage analog signal

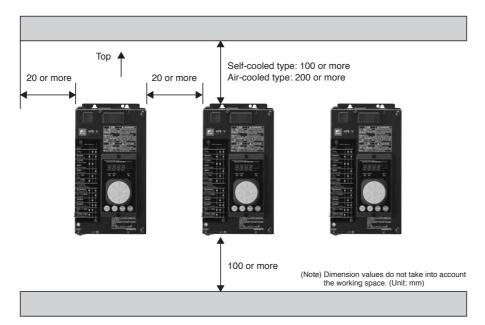
Category	Name	Symbol	When not in use	Function description		
Control power supply	Control power supply terminal	L (R1), N (T1)	-	Control circuit power supply Single-phase 100 V to 240 V AC input		
Input power supply detection	Input power supply detection terminal (Single-phase 400 V products only)	L0 (R0), N0 (N0)		Input power monitored using in-phase input with main circuit power supply		
Control circuit	Manual setting input	1, 2, 3	Open	Manual setting input and HIGH setting input using connection of variable resistor		
	Gradient setting input	1A, 2A, 3A	2A-3A short circuit	Gradient setting input and LOW setting input using connection of variable resistor		
	Automatic setting input	4C, 5V, M0	Open	Voltage and current signal input of controller		
	Auto/manual	AUTO, COM	-	Automatic setting input when the external contact is closed		
	switchover input			Manual setting input when the external contact is open		
	RUN / STOP input	RUN, COM	Short circuit	RUN status when the external contact is closed and output OFF when the external contact is open		
	Alarm reset	RST, COM	Open	Alarm release when the external contact is closed		
	Alarm contact output	Z1, ZC		Internal contacts turn ON when alarm occurs for major failure		
	Alarm contact output	Z2, ZC		Internal contacts turn ON when alarm occurs for minor failure		
	External detection input	U (+), V (-) 21 (+), 22, 23 (-)		Feedback detection input with connection of VT and various DC converters		
	External CT input (single-phase only)	CT1K, CT1L		CT connection using advanced heater disconnection alarm		
	External selection input (three-phase only)	ESEL, COM				
Parallel operation/	APD I/O	APD		Sending and receiving setting values with connection of a setting indicator (APD3)		
Modbus RTU/ CC-Link				Receiving parallel operation signals from previous-stage APR in parallel operation		
	Parallel run I/O	NET IN NET OUT		Sending and receiving setting values from the host in network communications		
				Sending parallel operation signals to next-stage APR in parallel operation		
		4A, MA		MX and MX2-series compatible input terminal		
		4B, MB		MX and MX2-series compatible output terminal		

(Note) The function description for the control circuit applies when there are no changes in function allocations.

APR-V

Mounting method

- To ensure heat radiation from APRs, mount the APR on a vertical metal surface, make sure the vertical mounting direction is as shown in the figure below, and provide sufficient space both vertically and horizontally. In particular, when using APRs in a dense configuration, there may be heat interference between APRs, so when mounting APRs, separate them by at least the dimensions shown below.
- The temperature inside the panel rises due to the heat generated by the APR, so please take measures to ensure ventilation, etc.
- · The left and right sides and top of the APR radiate the most amount of heat, so be careful of the impact of temperature rise on nearby objects.
- Ensure sufficient space with regard to nearby objects when wiring the main circuit terminals, control power supply terminals, and control circuit terminals, as well as for tools used in replacing quick-acting fuses (removing and replacing screws on front panel) and replacing cooling fans (removing and replacing fan mounting screws on the top).
- · The mounting interval of the APR is the same for single-phase and three-phase units.



Mounting space diagram

• Wiring method

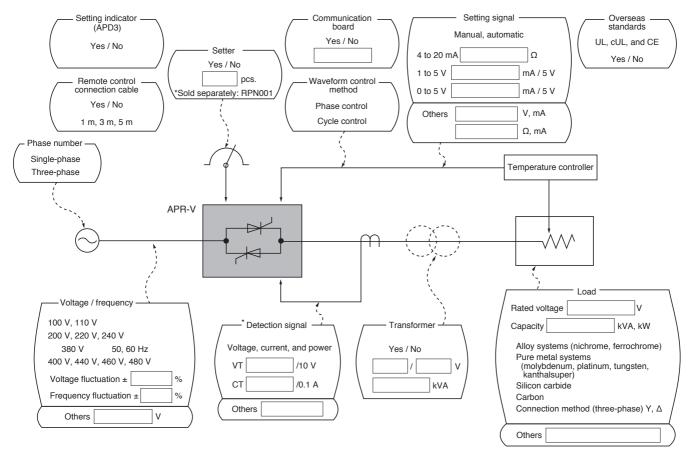
- For main circuit terminals (single-phase: L1, U; three-phase L1, L2, L3, U, V, W), use the screws (bolts) provided. Parts with dimensions larger than the specified dimensions will lack sufficient insulation from surrounding parts. Also, use insulation caps for crimp terminals.
- To ensure safety, always connect the ground terminal. Since this terminal is similar to the main circuit terminal, be careful not to mistake them. Wire the ground terminal independently and ensure that you do not wire more than one line.
- Use circuit protective circuit breakers or earth leakage circuit breakers on the main circuit input side and control power supply input side for short circuit protection and overload protection.
- The input power supply detection terminal of single-phase 400 V products monitors the main circuit power supply status. Wire the input power supply detection terminal block (single-phase: L0, N0) so that it is in-phase with the main circuit power supply.
- · The main circuit terminal of three-phase products monitors the main circuit power supply status.
- Wire so that the phase order of the main circuit power supply is $L1 \rightarrow L2 \rightarrow L3$.
- When wiring to control power supply terminal blocks (L, N), input power supply detection terminal blocks, and control circuit terminal blocks (Z1, Z2, ZC terminals), use crimp terminals with sufficient insulation coating to ensure insulation with nearby terminals.
- When wiring to the signal terminals of the control circuit terminal block, in order to prevent noise, do not wire them close to the main circuit terminals (single-phase: L1, U; three-phase: L1, L2, L3, U, V, W) and control power supply terminals (L, N), and do not wire them in the same duct. If the wires intersect, arrange them orthogonally. The wires should be twisted for each signal group (twist 4 to 7 times per 10 cm). When using a shielded wire, connect the shielded outer jacket on the receiving side to the ground terminal and leave the other terminal open.
- · For contact specifications of relays used for contact input, use twin gold-plated contacts for long-term continuous energization at low currents and voltages.
- · For external detection signal terminals (single-phase: U (+), V (-), CT1K, CT1L; three-phase: 21 (+), 22, 23 (-)), use a CT, VT, or insulating converter to isolate the signal from the main circuit.
- · When mounting the setter (type: RPN001), mount it after drilling mounting holes to prevent rotation.
- When connecting the setting indicator, secure it after taking into account the cable take-out direction so that no excessive force will be applied to the cable connector connection.

• Others

- In terms of output measurement instruments, use an RMS value type instrument for phase control and a cycle control waveform type instrument for cycle control. The use of other instruments will cause errors.
- · Please understand that no compensation will be provided for damages caused by the failure of any individual delivered product.

Inquiries

1. Please circle the appropriate content for each relevant item. Please fill in the values or details in the enclosed blank spaces.



*Select the following control method according to the detection signal.

- T: No feedback function
- A: AC CLR (current limit regulation)
- B: AC ACR (automatic current regulation) + AC CLR (current limit regulation)
- C: AC AVR (automatic voltage regulation) + AC CLR (current limit regulation)
- D: AC AWR (automatic wattage regulation) + AC CLR (current limit regulation)
- E: DC feedback control + AC CLR (current limit regulation)
- P: Transformer primary control via cycle control (single-phase only)

2. Surrounding temperature (panel inside temperatur	e when stored in-panel) to °C
3. Order type (= Product code)	
RPV 🗌 🗌 🗌 – 🗌	
4. Quantity: pcs.	⇒The following can be omitted depending on the specifications.
5. Delivery date: YYYY MM	DD
6. Company name	

7. Other remarks

MEMO



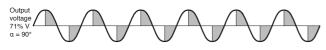
Fuji AC Power Regulator [APR] APR-D Series (Single-phase)

The single-phase APR-D Series is the successor to the APR-aB and aC. It is a space-saving, wiring-saving, low-cost APR with greatly improved functionality and performance thanks to its built-in CPU.

Features

- Applicable to inductive loads, transformer primary control, and rectifier primary control through continuous comb-tooth pulse control.
- · Able to switch the waveform control method (phase control, cycle control, and phase angle proportion control).

Phase control (0 to 100%)



Cycle control (intermittent control)

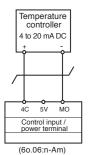


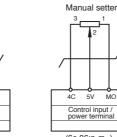
Example of control input wiring

For auto setting or manual setting only, it is possible to adjust the device by changing the function of the control input terminal block.

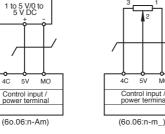
Temperature controller

4C





Gradient Temperature controller setting 4 to 20 m DC to 5 V DC 5V мо 4C Control input / power termina 60.06:n-Am 2h 02:5Vm0



(Note) When shipped from the factory. 60.06 is set to n-Am. and 2b.02 is set to Aod. Function codes and terminal functions are shown in parentheses ()



- Achieves space savings thanks to a class-minimal dense array (minimum interval in width: 2 mm).
- Base load setting, digital settings including gradient setting, and monitor functions are available as part of the standard configuration.

Operation example	Setting mode	
Monitor mode	Function code	Function code data

- Allows soft start time, soft up time, and soft down time to be individually set between 0 to 100.0 seconds.
- Performs auto identification of 100 to 240 V AC and 50/60 Hz with respect to control power.
- As a control method, current limit control and automatic current feedback control are available. You can also detect heater disconnection (cycle control: load opening)
 - (Note) It is possible to detect disconnection of one to three lines in an alloy heater where there are small changes in resistance depending on the temperature.
- Allows communication control as an optional function. Main unit option type:
 - ZAP: Up to 50 units can be operated in parallel.
 - For cycle control, a flicker prevention function is available. ZAM: Various settings and monitors are possible by means of RS485 (Modbus RTU).
- All models are compliant with CE marking / EU revised RoHS Directive (2011/65/EU+(EU)2015/863).



Compliant with the new EMC Directive (2014/30/EU) Compliant with the new Low Voltage Directive (2014/35/EU)

Complies with revised Chinese RoHS

All single-phase APR-D Series models are supported as standard.



Code

Blank

Code Blank

1

2

3

Code

Т

Α

В

(5) Control method

No feedback function

AC ACR + AC CLR

CLR: Current limit regulation ACR: Automatic current regulation

AC CLR

Z** (Note 3)

Order specifications (explanation of order types)

(1) Model classification

Code

RPD

Code

Code

Е

2

Mode

APR-D Series

Single-phase

Input voltage

100 to 240 V

(3) Input voltage

(2) Phase number

RPD E 2 0 6 0 - T 1 - ZAM (Note 1)

(7) Specifications
Specifications
Standard
Optional accessories for main unit
(6) Setter (Note 2)
Setter
None
Setter: 1 set
Setter: 2 sets
Setter: 3 sets

(4) Rated current

Rated current	Code
20 A	020
45 A	045
60 A	060
100 A	100

(Note 1) For the order codes which are blank, please fill it in with a hyphen " - ".

(Note 2) One set of setters is composed of a variable resistor, nameplate, control knob, and attachment sheet. The format of the separate order is "RPD001". It is not shown on the main unit type (Note 3) For options of the main unit, it is possible to specify multiple specification items like RPDE2020-T1-ZAM45.

Option specification name	Content	Туре
Communication board) Supports parallel run	Parallel run communication board mounting with anti-flicker function (Note 4)	RPDE2
Communication board) Supports network connections	Modbus RTU communication board mounting	RPDE2
Main circuit power ON soft start	Soft start through main circuit power ON is possible. (Pure metal load can be handled.) (Note 5)	RPDE2

(Note 4) The parallel run function provided by this communication board is not compatible with models other than the APR-D series

(Note 5) When the APR is to be connected with the secondary side of a transformer, this option type is not applicable

(Note 6) Note that main unit options are attached before shipment.

Rating, type / product code

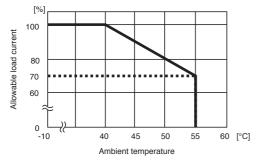
Phase number	Input voltage	Output current [A]	Type (= product code)
Single-phase	100 to 240 V	20	RPDE2020-T
	Common		RPDE2020-A
		45	RPDE2045-T
			RPDE2045-A
		60	RPDE2060-T
			RPDE2060-A
		100	RPDE2100-T
			RPDE2100-A

(Note) The price does not include a setter set and the main unit's options. The price of control method B types are the same as control method A types

Important notes in selecting products

Allowable load current - ambient temperature characteristics

The reference ambient temperature for the rated current is 40° C. When it exceeds 40° C, reduce the load current as below:



Main unit options

After delivery, addition and modification are not allowed for the type (= product code). Please remember this when placing an order.

• Fast-acting fuse

The main circuit does not contain a fuse. Use a fast-acting fuse depending on the capacity.

Selection of rated current

Considering that a large inrush current flows in an incandescent lamp or pure metal heater (a current that is several to ten times larger than a steady-state current for approximately 1/20 seconds to several seconds), choose the rated current very carefully.

- Transformer primary control (rectifier primary control)
 - (1) If there is a risk of the transformer becoming unloaded, connect a resistor in parallel with the primary winding so that about 0.5 A flows through it.
 - (2) Allow enough margin for magnetic flux density to prevent bias magnetism. (1.0 to 1.2 T or less)
 - (3) Even if the power supply voltage falls below -15%, APR-D output is maintained. Recovery of the power supply voltage may result in overcurrent caused by the bias magnetism phenomenon.

• Important notes for power cycle life expectancy

If RUN and STOP are repeated at short-period cycles (for example, 30-minute RUN and 30-minute STOP), a large difference in temperature will occur in the thyristor element, significantly shorting its life expectancy through thermal fatigue.

If such operations are needed, try to minimize the temperature fluctuation. Specifically, reduce the use rate of rated current to less than 80%. Or, choose an APR whose rated current is one level higher, so that the use rate of rated current is less than 80%.



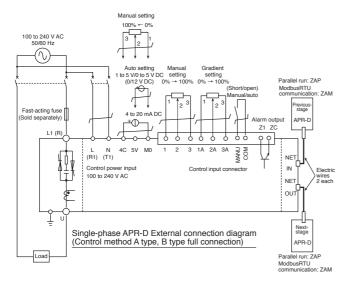
Specifications

Item			Specifications				
Type (product code)		RPDE2020-	RPDE2045-	RPDE2060-	RPDE2100-	
Input	Main circuit / control circuit	Rated input voltage and frequency	Single-phase 100 to 240 V AC 50 Hz/60 Hz (auto identification)				
		Input voltage range	Rated input voltage ±10% (Performance guarantee) (Note 1) Rated input voltage ±15% (Operation guarantee)				
		Input frequency range	50 Hz/60 Hz ±2.5 Hz				
	Control circuit	input capacity	15 VA or less				
nt	Rated current (at ambier	nt temperature 40°C) [A]	20	45	60	100	
Output	Cooling system		Self-cooled			1	
0	Applied load		Resistive load, inductive load,	transformer primary control, re-	tifier primary control (For cycle o	control, resistive load (alloy) only)	
	Minimum load current		0.5 A (However, at 100% outpo	0.5 A (However, at 100% output at the rated input voltage)			
	Generated loss (at rated	current) [W]	30	55	70	110	
Control	Waveform control metho	d	Single-phase thyristor anti-par Phase control / cycle control (i	allel connection ntermittent) / phase angle prop	ortion control		
Ő	Output voltage adjustme	nt range	0 to 100% (RMS value) of the	main circuit power supply volta	ge (excluding thyristor voltage dr	op portion)	
	Input-output characterist	ics	Linear characteristic of RMS v	alue, linearity : ±5% FS or less Linearity: ±5% FS or less		sistive load / setting signal 10 to 90%)	
-	Setting signal	Auto setting	Current signal : 4 to 20 mA DC Voltage signal : 0 to 5 V DC, 1 SSC signal: 0/12 V DC (Zin =	to 5 V DC (Zin = 11 kΩ)			
		Manual setting	External variable resistor: 1 k	(B characteristic 1/2 W or high	ier)		
		Digital setting	Front key input (direct drive po	ssible)			
		HIGH-LOW setting	Can be combined with digital	etting and external variable res	istor		
		(Two-position control)	Switching contact signal via di	gital setting or external contact	switching via control input conne	ector	
-	Gradient setting	Setting range	0 to 100% of output voltage				
		Setter	Voltage signal setting through digital setting, external variable resistor 1 k Ω , or control circuit terminal (5V-M0) (1 to 5 V DC Enables reverse gradient characteristics in combination with base load setting				
	Base load setting	Setting range	0 to 100% of output voltage				
		Setter	Digital setting				
	Soft start time Soft up time	Setting range	Control method T, A types : 0 to 100 seconds Control method B : 0.5 to 100 seconds (Note 2)				
	Soft down time	Setter	Digital setting. Each time can I	be individually set			
	Feedback control method (Phase control only)		AC CLR (Types with control method A) AC ACR + AC CLR (Types with control method B) (prioritizes AC CLR)				
	Manual/auto Switching s	ignal	Non-voltage contact				
ation te 4)	Parallel run Master/slave	•	Maximum number of connectible units: 50 Main unit's option type "ZAP" (Not compatible with the APR-N Series)				
Communi- cation (Note 4)	Network communication		RS-485 compliant Two-wire system Half duplex start-stop synchronization Protocol: Modbus RTU compliant Maximum number of connectible units: 31 Main unit's option type "ZAM"				
on	CPU memory error		CPU memory error detection a	CPU memory error detection at startup			
tect	Power supply error		Detects control power frequen	cies other than 45 to 65 Hz			
pro	Auto setting input not co	nnected	Detection of non-connection of current signal (4 to 20 mA DC) and voltage signal (1 to 5 V DC) (Only with auto setting)				
and	Manual setting input not	connected	Detection of non-connection of	a manual setter (external varia	ble resistor) (Only with manual s	setting)	
tion	Gradient setting input no	t connected	Detection of non-connection of a gradient setter (external variable resistor or 1 to 5 V DC)				
etec	Reverse phase detection				er phase are reverse (Main unit'	s option type "Z45" only)	
Error detection and protection	Data writing/reading erro	r	Detection of read/write errors				
Erro	Thyristor abnormality			hrough built-in CT (Types with			
	Communication error				AM") at the time of parallel run or		
	Current limit detection		Detects load current exceeding the CLR setting value and switches the phase angle to reduce it to within the CLR setting value (Types with control methods A, B)				
	Heater disconnection		Detection of APR output current values lower than the disconnection determination value (types with control methods A, B) (Note 3)				
	Alarm output		Open collector 24 V DC/ 0.1 A 1 circuit				
tting 1ent	Ambient temperature		-10 to +55°C (reduces load current to the rated current value when the temperature is between +40°C and +55°C)				
pera	Storage temperature		-20 to +60°C	· 、			
Operating environment	Ambient humidity			+5 to +95% RH (no condensation)			
	Others		1000 m or less	stances and actions that promo	te insulation deterioration, or vib	ration. Use indoors at an altitude of	
Insu- lation	Dielectric strength (Main		2000 V AC for 1 minute				
<u> </u>	Insulation resistance (To	ground)	10 MΩ or higher, measured wi	th 500 V DC megger tester			

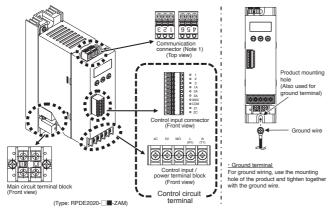
(Note 1) Performance guarantee refers to satisfying specifications and assuring proper run of the product. Operation guarantee refers to assurance of damage-free parts and proper run of the product. (Note 2) Soft start and soft up/down time for types with control method B are disabled even if set to a time which is shorter than the response speed in terms of PI control. This is because PI control is prioritized over soft start and soft up/down time.

(Note 3) For cycle control, load open detection is performed. (Note 4) Only one type of communication board can be mounted before shipment

Connection diagram



· Positions and functions of connection terminals



(Note 1) It is provided when the main unit option (ZAP, ZAM) is specified.

Screw size and tightening torque

Terminal		Screw size	Tightening torque [N ⋅ m] ±10%
Main circuit terminal	L1 (R), U	20 A M4	1.8 (18 kgf · cm)
block		45 A M5	2.7 (27 kgf · cm)
		60 A M5	
		100 A M8	12.0 (120 kgf · cm)
Control input · Power terminal block	L (R1), N (T1), 4C, 5V, M0	M3	0.5 (5 kgf • cm)
Control input connector	1 to ZC	-	-
Communication connector	NET IN, NET OUT		
Main unit mounting scr	ews (also used for the	20 to 60 A, M5	3.5 (35 kgf · cm)
ground terminals)		100 A M6	5.8 (58 kgf · cm)

Other options (sold separately)

• Replacement adapter for APR-αB and αC (RPD002-E

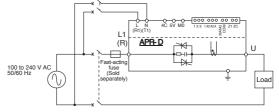
Туре	Content
RPD002-E02	For RPDE2020-
RPD002-E06	For RPDE2045- , RPDE2060-
RPD002-E10	For RPDE2100-

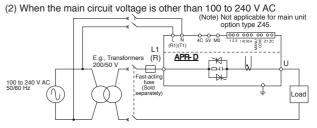
(Note) Attach the adapter to the mounting holes (for APR- α B and α C) on the panel surface, and then attach the APR-D to the adapter. For RPCE2020- , please apply RPD002-E06.

Fast-acting fuse

Wiring of the main circuit terminals and control power
terminals

(1) When the main circuit voltage is 100 to 240 V AC





Terminal function

Termin	al type		Symbol	Name	Function description	
Termin		Pin	Cynioon	100.110		
position						
Main c		-	L1 (R)	Main circuit	L1 (R): Main circuit power input	
Termin	al	-	U	terminal	U: APR output (connected to load)	
block		-	-	Ground terminal	Main unit's ground terminal (shared mounting hole)	
al	Зa	-	4C (3)	Automatic	4C-M0: 4 to 20 mA DC input;	
Control circuit terminal	Control input / power terminal block	_	5V (2)	setting input (Function code 60.06 = n-Am (factory default)	$\begin{array}{l} (Zin = 100 \ \Omega) \\ \text{SV-M0:} 1 \ to \ 5 \ V \ DC; \\ 0 \ to \ 5 \ V \ (SSC \ signal: \ 0/12 \ V); \\ (Zin = 11 \ k\Omega) \\ \text{SV-M0 can be allocated to the gradient} \\ \text{setting input of } 1 \ to \ 5 \ V \ DC \end{array}$	
Contre	Control Control		Manual setting input (Function code 6o.06 = n-m_)	Connecting a variable resistor makes it possible to use as manual setting input "When using this terminal as manual setting input, detection of manual setting non-connection is not performed		
	0	-	L (R1)	Control power	Control power input. Input the same phase	
		-	N (T1)		as that of the main circuit	
	to	b 1 1 Manual setting	Manual setting	Connecting a variable resistor makes it possible to use as manual setting input		
	Jec	2 2 In			Input	
	ino 1	3 4	3 1 A	Our dia state a differen		
	rto	4 5	1 A 2 A	Gradient setting	Connecting a variable resistor makes it possible to use as gradient setting input	
	iduj	6	2 A 3 A	input	possible to doe do gradient ootting input	
	2	7	MANU	Auto/manual	External contact Open: Auto setting	
	Control input connector	8	COM	switching	Closed: Manual setting	
		9	Z1	Alarm output	When an alarm occurs, the internal open	
		10	ZC	Terminal	collector turns ON. Operation can be selected by changing the function code setting.	
al)	ਜ਼ ਦੇ 1,2 NET IN RS-485			When in network communications (option		
connect (Option;	Network	4, 5	NET OUT	Input-output	type: ZAM), various kinds of data are sent to and received from a host using the ModbusRTU protocol.	
Communication connector (Optional)	Parallel run	1, 2	NET IN	Parallel run input	When in parallel run (option type: ZAP), parallel run signals are received from the previous-stage APR.	
Commu	Para	4, 5	NET OUT	Parallel run output	When in parallel run (option type: ZAP), parallel run signals are sent to the next-stage APR.	

• DIN rail-mounting adapter

Туре	Content
RPD004-E02	DIN rail-mounting adapter for RPDE2020-

Rated current (APR type)	Fast-acting fuse (rated current)	Fast-acting fuse holder	Base and cap				
20 A (RPDE2020)	CR2LS-30 (30 A) or BLC045-1 (45 A)	CM-1A	AFa60 + Pa60 (for BLC)				
45 A (RPDE2045)	CR2LS-75 (75 A) or BLC075-1 (75 A)	(For CR2LS, tripolar product)	AFa100 + Pa100 (For BLC)				
60 A (RPDE2060)	CR2LS-100 (100 A) or BLC090-1 (90 A)						
100 A (RPDE2100)	CR2L-150 (150 A)	CM-2A (Tripolar product)	-				



APR-D Series (Single-phase)

The standard configuration of the APR-D Series contains display/operation units for various monitors and settings.

Names and functions of the individual parts

Name	Function	Name	Function	Data display
Drive monitor	Data display unit 4th digit DP Run output Presence (light up) / absence (turn off)	UP key DOWN key	Use to select run information shown on the data display unit and to change the function code data. *Press and hold for one second or longer to perform auto switch of the data display.	
Data display	 4-digit 7-segment LED monitor Displays the following information for each operation mode. During MON (monitor) mode Run information (Output instruction value, output current, input signal, etc.) Displays the alarm code when an alarm occurs. The 4th digit shows items for various types of run information. During SET mode Displays function code and function code data, etc. 	MODE/SET key	Use to switch the operation mode. • During MON (monitor) mode Press and release to switch to the setting mode. • When selecting a function code in setting mode Press and release to switch to function code data display. Press and hold for 1 second or longer to switch to the monitor mode. • When setting function code data in setting mode • Press and release to confirm data. • Press and hold for 1 second or longer to cancel	
Alarm lamp	Data display unit 1st digit DP Alarm Presence (blink) /absence (turn off)		the setting and return to the monitor mode.	MODE/SET key

Monitor mode

Operating the UP and DOWN keys causes the monitor items below to be shown. (The alarm code is shown only when a failure occurs.)

		_			
~	Output instruction value		Alar	m code	
	- I D	□. ←		Έ_	EL.
	Output current		Auto	simanual	ţ
	'A 2 0	. 0.		Έ	<u> </u>
	Power frequency	(ڰ	dient setting	1
	`НБ D	. 0. (ຈົ	Γí	00.
	Î Î		- Gut Sign	put setting al	Į –
	L			- I	00.

No.	Monitor item	Function Item Display	Display	Unit			r icy (Note)	
		Dispiay				Т	A/B	
1	Output instruction value	0	100	%	Output instruction through APR internal calculation	0		
2	Output current	A	20	A	AC output current detection value	-	0	
3	Power frequency	Н	60.0	Hz	Power frequency detection value	0		
4	Output setting signal	r	100	%	Each setting signal detection value	0		
5	Gradient setting signal	G	100	%	Gradient setting signal detection value	0		
6	Auto/manual switching	t	At/m1/m2	-	Auto/manual switching terminal status display	-		
7	Alarm code	E	_SM	-	Display at the time of alarm occurrence	-		
(Note	(Note) Monitor accuracy:○ = 5%							

Power on

Setting mode

(

;

100

80

40

200

It is possible to set and confirm the data below for each item:

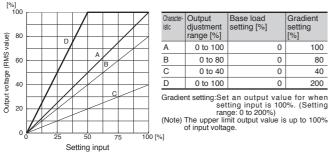
- Drive monitor

11 10 1								
Category	Display	Setting item	Description of the main functions					
Data	1b	Basic function 1	Setting to be used for basic APR					
setting		b code (1b.01 to 1b.06)	operations					
			Mainly replacing external volume					
	2b	Basic function 2	Setting to be used for basic APR					
		b code (2b.01 to 2b.07)	operations					
			Mainly function selection					
	3F	Feedback function	Setting related to feedback					
		F code (3F.01 to 3F.08)	CLR setting, heater disconnect function					
	4n	Network function	Communication settings					
		n code (4n.01 to 4n.08)						
	5A	Alarm function	Alarm output (control input connector)					
		A code (5A.01 to 5A.09)	setting					
Setting	60	Setting option function	Utility function setting					
option		o code (60.01 to 60.07)	(Display of function codes changed					
			from factory defaults and restriction of					
			operations of the setting indicator)					
Initial	0i	Initial setting function	Type setting, ROM version confirmation					
setting		i code (0i.01 to 0i.05)						

• Example of setting groups

Function	Name	Function code data	Step size	Unit	Factory default
code		(Settable range)			setting
1b.01	Manual digital setting	0 to 100.0 [%]	0.1	%	0
1b.02	Gradient digital setting	0 to 200.0 [%]	0.1	%	100.0
1b.03	Base load setting	0 to 100.0 [%]	0.1	%	0
1b.04	Soft start time setting	T, A types: 0 to 100.0 [seconds]	0.1	seconds	0.5
1b.05	Soft up time setting	B type: 0.5 to 100.0 [seconds]	0.1	seconds	0.5
1b.06	Soft down time setting]	0.1	seconds	0.5

· Gradient setting / base load setting



[9	%] 100									
	80		E			F	2			(i:
Output voltage (RMS value)	60			\times				G		
t voltage	40					\geq	\leq			E
Output	20	2						$\overline{\langle}$		A fi ∨ li
	00					_			\square	
	(J	2	25 S	5 ettin	io g inp		5	10	0 [%]

100

90

80

60 current

50

40 Output

30

20

10

0

10 20 30 40 50 60 70 80 90 100

[% A] 70

Chara Output Base load setting [%] Gradient istic djustment setting range [%] %1 Е 100 to 0 100 0 F 50 to 100 50 100 G 20 to 60 20 60

Base load:Set an output value for when setting input is 0%. (Setting range: 0 to 100%) Actual output represents characteristics resulting from the connection between a base load setting value and gradient setting value using a straight line.

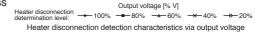
Heater disconnection detection (Types with control methods A, B)

Heater disconnection is detected when the load current drops lower than the current value set with the heater disconnection determination level.

- · Applied heater: Alloy heater (Load which flows 40 to 100% of the rated current when
- the output voltage is 100%)
- · Number of parallel lines: 1 to 3 lines (The material and capacity must be identical.)
- · For phase control / phase angle proportion control When setting less than 5%: Disconnection determination invalid

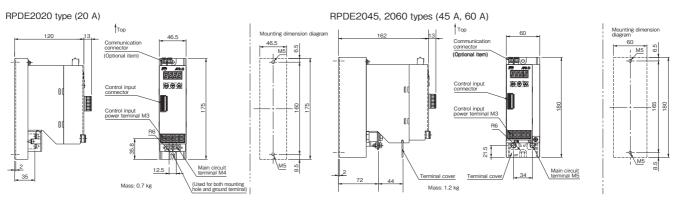
When setting 5% or higher: Disconnection is detected when the output current is approximately 5 to 100% of the rated current.

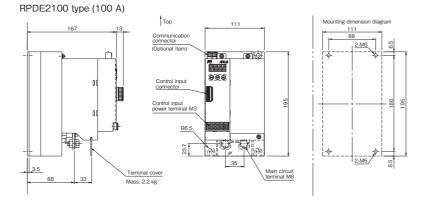
- · For cycle control
 - When setting less than 5%: Disconnection determination invalid When setting 5% or higher: Load open is detected when the output current is less than approximately 5% of the rated current.
- · Determination range: 30 to 100% of the output instruction value
- Determination accuracy: ±5% FS or less



Phase control / phase angle proportion control Allov heater

External dimension diagram [Unit: mm]



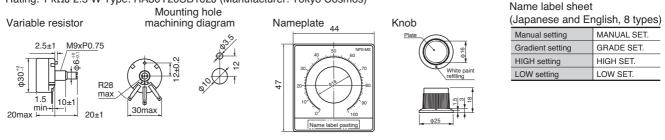


Supplied items (If specified in ordering information)

Setter type: RPD001

Used in setting method "variable resistor setting, two-position control, gradient setting," etc.

Rating: 1 kΩJ 2.5 W Type: RA30Y20SB102J (Manufacturer: Tokyo Cosmos)



Important notes for installation

- (1) Install in a dust-free place with high cooling effect. To ensure heat radiation from APRs, mount the APR on a vertical metal surface, make sure the vertical mounting direction is as shown in the Figure 1, and provide sufficient space both vertically and horizontally. If placing APRs closely to one another, ensure sufficient space beyond the dimensions indicated in Figure 1 to reduce heat interference among the APRs.
- (2) Heat generation of an APR raises the temperature inside the panel. In consideration of expected temperature rises, implement measures such as cooling and ventilation. (The maximum temperature inside the panel is 55°C.) The reference ambient temperature for the rated current is 40°C. When it exceeds 40°C, reduce the load current.
- (3) Ensure sufficient space with nearby objects in consideration of the work space required for wiring tools at individual terminals.
- (4) The top of an APR has a partial opening. Be careful not to drop any object into the opening.

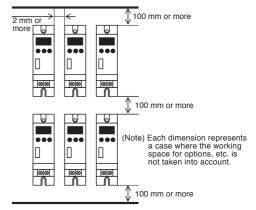


Fig. 1 Installation spacing



The three-phase APR-D Series is the successor to the APR-L. It is a space-saving, wiring-saving, low-cost APR with greatly improved functionality and performance thanks to its built-in CPU.

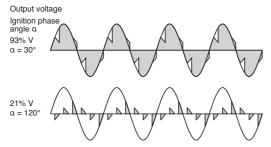


Features

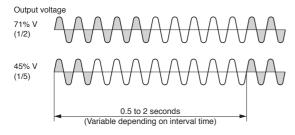
- This is a thyristor pure anti-parallel system (six-arm).
- The output range is 0 to 100% of the main circuit power supply voltage.

Excluding the voltage drop portion due to thyristor-specific resistance

- Able to switch the waveform control method (phase control, cycle control, and phase angle proportion control).
 - Phase control method (0 to 100%)

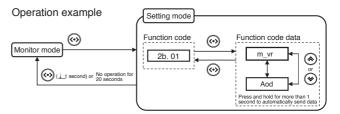


Cycle control method (continuous)



- The main circuit terminal block comes with a cover attached.
- The mounting pitch is the same as for APR-L. However, this excludes 400 V, 45/60 A products.
- Output for various settings represent linear characteristics of RMS values.

• Base load setting, digital settings including gradient setting, and monitor functions are available as part of the standard configuration.



- Allows soft start time, soft up time, and soft down time to be individually set between 0 to 100.0 seconds.
- When power to the main circuit is turned ON, soft start is always activated.
- The power supply voltage ranges are 200 to 240 V AC and 380 to 480 V AC.

(Note) An operational transformer is provided with 380 to 440 V AC products.

An operational transformer for 380 to 480 V AC products is a separately sold option.

- Allows communication control as an optional function. Main unit option type:
 - ZAP: Up to 50 units can be operated in parallel.
 - For cycle control, a flicker prevention function is available. ZAM: Various settings and monitors are possible by means of
- RS485 (Modbus RTU).All models of the APR units are compliant with the CE

marking / Compliant with the EU RoHS Directive (2011/65/EU + (EU)2015/863)

For 400 V products, the operational transformer needs to be modified to comply with the CE marking.



Compliant with the new EMC Directive (2014/30/EU) Compliant with the new Low Voltage Directive (2014/35/EU)

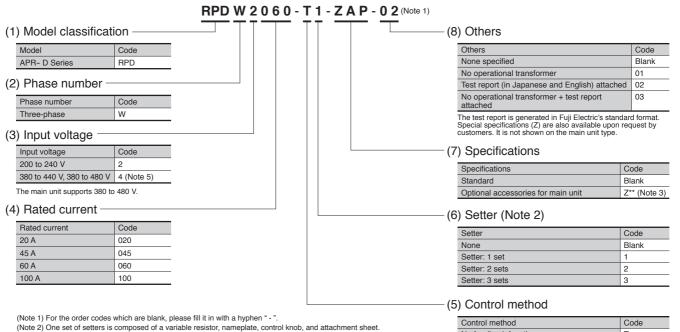
• Complies with revised Chinese RoHS

All three-phase APR-D Series models are supported as standard.



Т

Order specifications (explanation of order types)



The format of the separate order is "RPD001". It is not shown on the main unit type

(Note 3) Optional accessories for main unit (example)

Option specification name	Content	Туре
Communication board) Supports parallel run	Parallel run communication board mounting with anti-flicker function (Note 4)	RPDW
Communication board) Supports network connections	Modbus RTU communication board mounting	RPDW

(Note 4) The parallel run function provided by this communication board is not compatible with models other than the APR-D series. Does not support cycle control in combination with single-phase products.

(Note 5) For input voltage code "4", an operational transformer (ML3C2954) is supplied as part of the standard configuration.

For products which support 480 V or CE marking, add "-01" to the main unit's type and separately order "TR3-300R/UL" Order format example) RPDW4020-T1-01

Name	Transformer type	Rating (Primary voltage/ secondary voltage, capacity)
Operational transformer (standard)	ML3C2954	380, 400, 440 V/210 V 20 VA
Operational transformer (480 V compatible)	TR3-300R/UL	380, 400, 440, 480 V/220 V 300 VA

■ Rating, type / product code

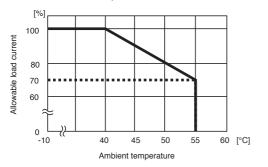
Phase number	Input voltage	Output current [A]	Type (= product code)
Three-phase	200 to 240 V	20	RPDW2020-T
		45	RPDW2045-T
		60	RPDW2060-T
		100	RPDW2100-T
	380 to 440 V	20	RPDW4020-T
		45	RPDW4045-T
		60	RPDW4060-T
		100	RPDW4100-T

(Note) The price does not include a setter set and the main unit's options.

Important notes in selecting products

Allowable load current - ambient temperature characteristics

The reference ambient temperature for the rated current is 40°C. When it exceeds 40°C, reduce the load current as below:



Main unit options

After delivery, addition and modification are not allowed for the type (= product code). Please remember this when placing an order.

No feedback function

Fast-acting fuse

The main circuit does not contain a fuse. Use a fast-acting fuse depending on the capacity.

• Important notes for power cycle life expectancy If RUN and STOP are repeated at short-period cycles (for example, 30-minute RUN and 30-minute STOP), a large difference in temperature will occur in the thyristor element, significantly shorting its life expectancy through thermal fatigue. If such operations are needed, try to minimize the temperature fluctuation. Specifically, reduce the use rate of rated current to less than 80%. Or, choose an APR whose rated current is one level higher, so that the use rate of rated current is less than 80%

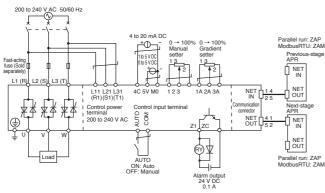


Specifications

Item		Specifications							
Type (product code)		RPDW_020-T	RPDW_045-T	RPDW_060-T	RPDW_100-T				
Input	Phase number		Three-phase						
dul	Main circuit	Rated voltage		200 to 240 V AC ±10% (Performance guarantee), ±15% (Operation guarantee) (Note 1) 380 to 480 V AC ±10% (Performance guarantee), ±15% (Operation guarantee) (Note 1)					
		Frequency	50 Hz/ 60 Hz ±2.5 Hz (Must be	50 Hz/ 60 Hz ±2.5 Hz (Must be the same as that of the control circuit.)					
	Control circuit	Rated voltage	200 to 240 V AC ±10% (Perfor	rmance guarantee), ±15% (Op	eration guarantee) (Note 1)				
		Frequency	50 Hz/60 Hz ±2.5 Hz (auto ide	entification)					
		Power capacity	15 VA or less						
out	Rated current (ambient te	emperature 40°C)	20 A	45 A	60 A	100 A			
Output	Cooling system		Self-cooled		·				
Ŭ	Applied load		Resistive load						
	Minimum load current		0.5 A (However, at 100% outp	ut at the rated input voltage)					
	Generated loss		75 W	155 W	196 W	317 W			
us	Waveform control metho	d	Phase control / cycle control (continuous) / phase angle prop	portion control	· · · · · · · · · · · · · · · · · · ·			
ictio	Output voltage adjustmen	nt range	0 to 100% of main circuit powe	er supply voltage (RMS value)	(Except thyristor voltage drop)				
Control functions	Input-output characteristi	cs	Linear characteristic of RMS va	alue, linearity: ±3% FS or less Linearity: ±5%FS or less	" (Howover at re-	sistive load / setting signal 10 to 90%)			
Con	Setting signal	Manual setting	External variable resistor: 1 kg	Digital setting: Setting with front keys External variable resistor: 1 kΩ (B characteristic 1/2 W or higher) HIGH/LOW (two-position control) contact signal: Digital setting through external wiring or front keys					
		Auto setting		Current signal: 4 to 20 mA DC (Zin = 100 Ω) Voltage signal: 0 to 5 V DC (SSC signal: 0/12 V DC), 1 to 5 V DC (Zin = 11 k Ω) (Setting change with front keys)					
	Gradient setting	Setting range	0 to 100% of output voltage						
		Setter	Digital setting: Setting with front keys External variable resistor: 1 kΩ (B characteristic 1/2 W or higher) Control input terminal "5V-M0" voltage signal: 1 to 5 V DC						
	Base load setting	Setting range	0 to 100% of output voltage						
		Setter	Digital setting: Setting with front keys						
	Soft start, up/down time	Setting range	0 to 100 seconds						
		Setter	Digital setting: Setting with fro	nt keys					
	Scanning interval	Setting range	0.5 to 2.0 seconds						
	setting	Setter	Digital setting: Setting with from	Digital setting: Setting with front keys					
uo	CPU memory error		CPU memory error detection at startup						
Alarm function	Power frequency abnorm	nality	Detects control power frequen	icies other than 45 to 65 Hz					
n fr	Auto setting input not cor	nnected (Note 2)	Detection of non-connection o	f current and voltage signals (Only with auto setting chosen for	setting signals)			
Aları	Manual setting input not	connected	Detection of non-connection o	Detection of non-connection of a manual setter (Only with external variable resistor chosen for manual setting)					
	Gradient setting input no	t connected	Detection of non-connection of a gradient setter (Only with external variable resistor or 1 to 5 V DC chosen for gradient setting)						
	Open phase / phase seq	uence failure	Detection of open phase or ph	Detection of open phase or phase sequence failure regarding the main circuit power and control power					
	Data writing/reading failu	re	Detection of read/write errors from/to EEPROM						
	Communication error (No	ote 3)	Detection of data transmission failure when in parallel run or network communications						
	Alarm output		Open collector 24 V DC/ 0.1 A 1 circuit						
ent	Ambient temperature		-10°C to +55°C (When +40°C	is exceeded, the load current	needs to be reduced.)				
erati	Storage temperature		-20°C to +60°C	-20°C to +60°C					
Operating environment	Ambient humidity		+5 to +95% RH (no condensat	tion)					
eu	Others		No corrosive gases (sulfide ga Use indoors at an altitude of 1		ubstances and actions that prom	ote insulation deterioration			
Insu- lation	Dielectric strength (Main	circuit to ground)	2 kV AC, 1 minute (200 to 240	V); 2.5 kV AC, 1 minute (380	to 480 V)				
Inte	Insulation resistance (To	ground)	10 M Ω or higher, measured w	ith 500 V DC megger tester					
(Note 1	a 1) Performance guarantee refers to satisfying specifications and assuring proper run of the product. Operation guarantee refers to assurance of damage-free parts and proper run of the product								

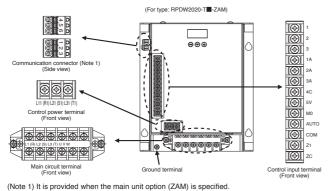
(Note 1) Performance guarantee refers to satisfying specifications and assuring proper run of the product. Operation guarantee refers to assurance of damage-free parts and proper run of the product. (Note 2) It does not operate when the voltage signal 0 to 5 V DC (0/12 V) is set. (Note 3) Option type: ZAP or ZAM only

Connection diagram



Three-phase APR-D External connection diagram (Full connection)

· Positions and functions of connection terminals



• Screw size and tightening torque

		· ·		
Terminal		Screw size		Tightening torque [N·m] ±10%
Main circuit	L1 (R), U	20 A product	M4	1.8 (18 kgf·cm)
terminal	L2 (S), V L3 (T), W	45 A product	M5	3.5 (35 kgf·cm)
	20 (1), 10	60 A product	M6	5.8 (58 kgf·cm)
		100 A product	M8	13.5 (135 kgf·cm)
Ground terminal		20 A product	M4	1.8 (18 kgf·cm)
		45, 60 A products	M5	3.5 (35 kgf·cm)
		100 A product	M6	5.8 (58 kgf·cm)
Control power terminal	L11 (R1), L21 (S1), L31 (T1)	20 to 100 A products	M3	0.5 (5 kgf·cm)
Control input terminal	1 to ZC	_	M3	0.5 (5 kgf·cm)
Communication connector	NET IN, NET OUT	-		_
Main unit mounting	screws	20 A product	M4	1.8 (18 kgf·cm)
		45, 60 A products	M5	3.5 (35 kgf·cm)
		100 A product	M6	5.8 (58 kgf·cm)

Other options (sold separately)

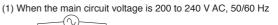
• Fast-acting fuse application table

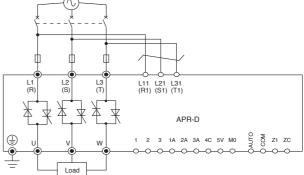
APR type	Rated Current	Voltage series	Fast-acting f	use type	Fast-acting fuse holder
RPDW2020	20 A	200 V	CR2LS-30	(30 A)	CM-1A (for 3-pole products)
RPDW4020		400 V	CR6L-30	(30 A)	CMS-4 (for 1-pole products)
RPDW2045	45 A	200 V	CR2LS-75	(75 A)	CM-1A (for 3-pole products)
RPDW4045		400 V	CR6L-75	(75 A)	CMS-5 (for 1-pole products)
RPDW2060	60 A	200 V	CR2LS-100	(100 A)	CM-1A (for 3-pole products)
RPDW4060		400 V	CR6L-100	(100 A)	CMS-5 (for 1-pole products)
RPDW2100	100 A	200 V	CR2L-150	(150 A)	CM-2A (for 3-pole products)
RPDW4100		400 V	CR6L-150	(150 A)	CMS-5 (for 1-pole products)

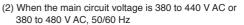
Туре Content

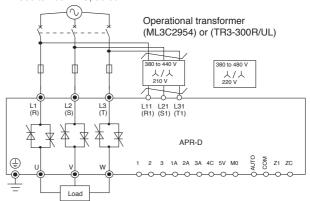
RPD002-W06 For RPDW4045- , RPDW4060-(Note)Attach the adapter to the mounting holes (for APR-L) on the panel surface, and then attach the APR-D to the adapter

• Wiring of the main circuit terminals and control power terminals





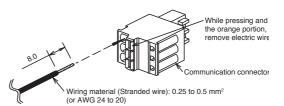




Terminal function

Termi	nal	Pin	Symbol	Name	Function description
	Main circuit Terminal		L1 (R), L2 (S) L3 (T)	Main circuit input terminal	Three-phase power input for the main circuit
		-	U, V, W	Main circuit output terminal	APR output. Connection of three-phase load
Groun		-	٩	Ground terminal	Main body grounding terminal
Contro power supply Termin	r V	-	L11 (R1) L21 (S1) L31 (T1)	Control power terminal	Control circuit power supply Three-phase 200 V to 240 V AC input
Contro		-	1, 2, 3	Manual setting input	Manual setting input through a variable resistor
Termi	nal	-	1A, 2A, 3A	Gradient setting input	Gradient setting input through a variable resistor
		-	4C, M0	Auto setting input	Auto setting input through 4 to 20 mA DC
			5V, M0		Auto setting input or gradient setting input through 1 to 5 V DC Auto setting input (SSC signal input) through 0 to 5 V DC (0/12 V)
		-	AUTO, COM	Auto/manual switchover input	External contact Closed: Auto setting Open: Manual setting
		-	Z1, ZC	Alarm output terminal	When an alarm occurs, the internal open collector turns ON. Operation selection is possible with function code 5A (alarm function).
ation	Network	1.2	NET IN	RS-485 input	Data reception and transmission from and to the master unit
Communication connector	_	4.5	NET OUT	RS-485 output	Connection with slave unit or connection of a terminating resistor
Domu	Parallel RUN	1.2	NET IN	Parallel run input	Data reception from the previous-stage APR
	Ра	4∙5	NET OUT	Parallel run output	Data transmission from the next-stage APR

Communication connector wiring example



APR-D Series (Three-phase)

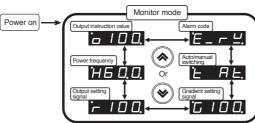
The standard configuration of the APR-D Series contains display/operation units for various monitors and settings.

•Names and functions of the individual parts

Name	Function	Name	Function	Data diaplay
Drive monitor	Data display unit 4th digit DP Run output Presence (light up) / absence (turn off)	UP key DOWN key	Use to select run information shown on the data display unit and to change the function code data. *Press and hold for one second or longer to perform auto switch of the data display.	
Data display	 4-digit 7-segment LED monitor Displays the following information for each operation mode. During MON (monitor) mode Run information (Output instruction value, input signal, etc.) Displays the alarm code when an alarm occurs. The 4th digit shows items for various types of run information. During SET mode Displays function code and function code data, etc. 	MODE/SET key	Use to switch the operation mode. • During MCN (monitor) mode Press and release to switch to the setting mode. • When selecting a function code in setting mode Press and release to switch to function code data display. Press and hold for 1 second or longer to switch to the monitor mode. • When setting function code data in setting mode • Press and release to confirm data. • Press and hold for 1 second or longer to cancel the	Alarm lamp
Alarm lamp	Data display unit 1st digit DP Alarm Presence (blink) /absence (turn off)		setting and return to the monitor mode.	MODE/SET key

• Monitor mode

Operating the UP and DOWN keys causes the monitor items below to be shown. (The alarm code is shown only when a failure occurs.)



No.	Monitor item	Function item display	Display	Unit	Display description
1	Output instruction value	0	100	%	Output instruction through APR internal calculation
2	Power frequency	Н	60.0	Hz	Power frequency detection value
3	Output setting signal	r	100	%	Each setting signal detection value
4	Gradient setting signal	G	100	%	Gradient setting signal detection value
5	Auto/manual switching	t	At/m1	-	Auto/manual switching terminal status display At Auto setting m1 Manual setting
			Hi/Lo	-	Two-position control status indication Hi HIGH setting Lo LOW setting
6	Alarm code	E	_Sm	-	Indication when an alarm occurs (Example: Manual setting input non-connection)

Setting mode

It is possible to set and confirm the data below for each item:

- Drive monitor

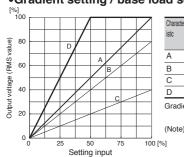
Category	Display	Setting item	Description of the main functions
Data setting	1b	Basic function 1 b code (1b.01 to 1b.07)	Setting to be used for basic APR operations Mainly replacing external volume
	2b	Basic function 2 b code (2b.01 to 2b.07)	Setting to be used for basic APR operations Mainly function selection
	4n	Network function n code (4n.01 to 4n.08)	Communication settings
	5A	Alarm function A code (5A.02 to 5A.09)	Alarm output setting
Setting option	60	Setting option function o code (60.01 to 60.04)	Utility function setting (Display of function codes changed from factory defaults and restriction of operations of the setting indicator)
Initial setting	0i	Initial setting function i code (0i.04 to 0i.05)	Communication protocol settings, ROM version check

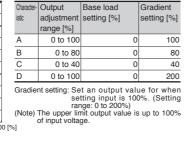
Setting item	Setting sigr	nal	Function code	Function code data
Auto setting	Current	4 to 20 mA	-	-
	signal	DC		
	Voltage	1 to 5 V DC	2b.03	1 to 5v (1 to 5 V DC)
	signal	0 to 5 V DC	(Auto setting Voltage signal	0 to 5v
			Selection)	(0 to 5 V DC (0/12 V))
Manual	Setting		2b.01	Aod (Setting indicator)
setting	indicator		(Manual setter selection)	
	External	1-2-3		m–vr (external variable
	variable			resistor)
	resistor			
Gradient	Setting		2b.02	Aod (Setting indicator)
setting	indicator		(Gradient setter	
	External	1A-2A-3A	selection)	G-vr (external variable
	variable			resistor)
	resistor			
	Voltage			5vm0 (Voltage setting
	signal			signal)
Slave unit		-	4n.01	no. 2– (Slave)
(ZAP)			(Master/slave selection)	

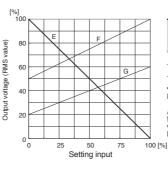
•Example of setting groups

Function code	Name	Function code data (Settable range)	Step size	Unit	Factory default setting
1b.01	Manual digital setting	0 to 100.0 [%]	0.1	%	0
1b.02	Gradient digital setting	0 to 200.0 [%]	0.1	%	100.0
1b.03	Base load setting	0 to 100.0 [%]	0.1	%	0
1b.04	Soft start time setting	0 to 100.0 [seconds]	0.1	seconds	0.5
1b.05	Soft up time setting		0.1	seconds	0.5
1b.06	Soft down time setting		0.1	seconds	0.5

•Gradient setting / base load setting







Character- istic	Output adjustment range [%]	Base load setting [%]	Gradier setting [%]	it
E	100-0	10	00	0
F	50-100	5	50	100
G	20-60	2	20	60

Base load: Set an output value for when setting input is 0%. (Setting range: 0 to 100%). Actual output represents characteristics resulting from the connection between a base load setting value and gradient setting value using a straight line.

External dimension diagram [Unit: mm]

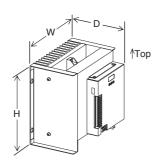
(1) External dimensions and mass

External dimensions

/	20 A	45 A/60 A	100 A		
W	185	240	291		
Н	215	265	345		
D	135	170	215		
Note) The external dimensions of the 200 V series and 400 V series are identical.					
Mass					

20 A	45 A/60 A	100 A			
2.6 kg	6.8 kg	10.0 kg			
Noto) The mass of the 200 V series and 400 V					

Note) The mass of the 200 V series and 400 V series is identical.



사

16 (E)

M6

(2) Mounting pitch (drilling)

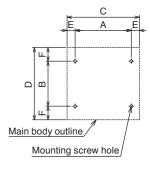
Mounting pitch

	20 A	45 A/60 A	100 A
A	170	222	270
В	145	165	245
С	185	240	291
D	215	265	345
E	7.5	9	10.5
F	35	50	50
Mounting screw	M4	M5	M6

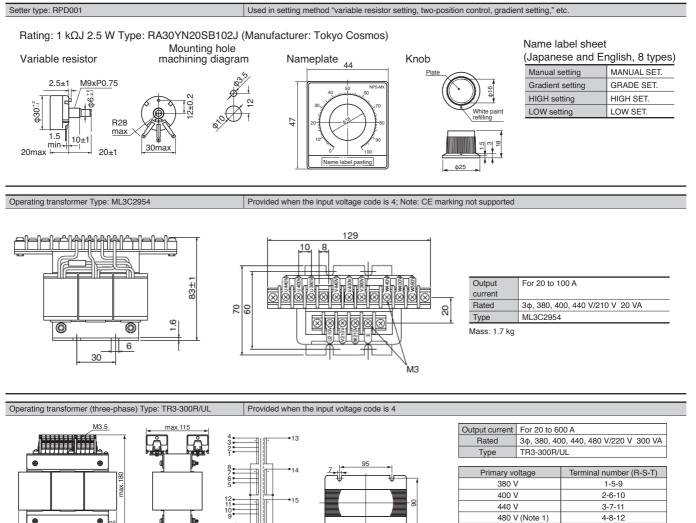
Note) The external dimensions of the 200 V series and 400 V series are identical.

Mass: 8.5 kg

(Note 1) Do not use it at 460 V or 480 V when the main unit is of the standard voltage specification.



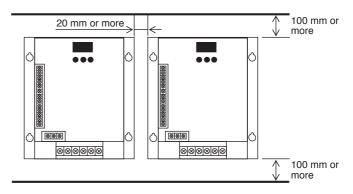
• Supplied items (If specified in ordering information)





Important notes for installation

- (1) Install in a dust-free place with high cooling effect. To ensure heat radiation from APRs, mount the APR on a vertical metal surface, make sure the vertical mounting direction is as shown in the figure on the right, and provide sufficient space both vertically and horizontally. If placing APRs closely to one another, ensure sufficient space beyond the dimensions indicated in the figure on the right to reduce heat interference among the APRs.
- (2) Heat generation of an APR raises the temperature inside the panel. In consideration of expected temperature rises, implement measures such as cooling and ventilation. (The maximum temperature inside the panel is 55°C.) The reference ambient temperature for the rated current is 40°C. When it exceeds 40°C, reduce the load current.
- (3) Ensure sufficient space with nearby objects in consideration of the work space required for wiring tools at individual terminals.
- (4) The top of an APR has a partial opening. Be careful not to drop any object into the opening.

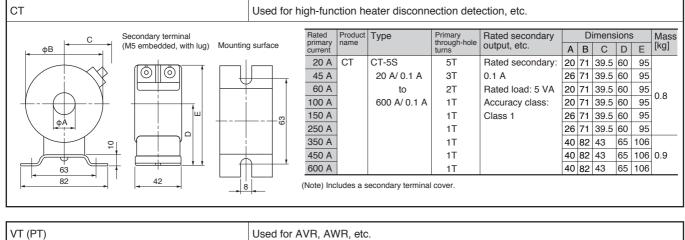


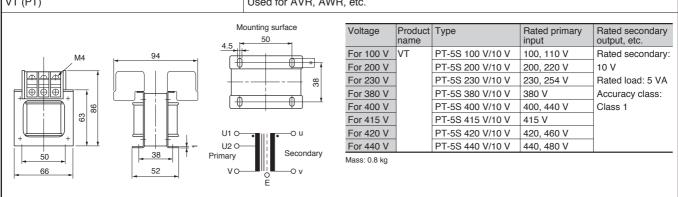
Installation spacing

MEMO



Fuji AC Power Regulator [APR] Option CT, VT





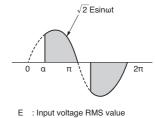


Selection of Instruments (Voltmeter, Ammeter, etc.)

Phase control method

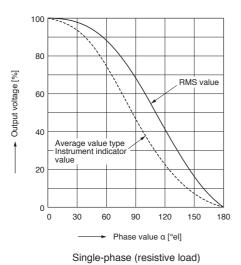
The voltage and current of AC circuits are generally expressed in RMS values, while moving-iron instruments are usually used as measuring instruments. However, some AC instruments, such as rectifier meters, digital meters, and testers, operate, in principle, by converting sine waveforms into average DC values. This can result

RMS value: Ee = $\sqrt{\frac{1}{\pi} \int_{a}^{\pi} \sqrt{2} \operatorname{Esin}\omega t}^{2} \cdot d(\omega t)}$ (1) Average value: Em = $\frac{1}{\pi} \int_{a}^{\pi} \sqrt{2} \operatorname{Esin}\omega t \cdot d(\omega t)$ (2) in incorrect RMS values being shown for APR phase-controlled waveforms. A supplementary explanation of this is given below. In other words, the ratio of the RMS value to the average value of the phase-controlled AC waveform will depend on the phase angle, as shown in the following equation.



E : Output voltage RMS value Ee : Output voltage RMS value Em : Output voltage average value a : Phase control angle

The following figure shows the calculation results of the above equation for single-phase and three-phase APRs.



100 80 Output voltage [%] RMS value 60 40 Average value type Instrument indicator value 20 0 0 30 60 120 210 90 150 180 Phase value α [°el] Three-phase (resistive load)

The following table summarizes the suitability of instruments.

Instrument operating principle and suitability for APR

Application	Instrument operating principle	Symbol	Suitability	Category
Voltmeter	RMS value calculation digital type	(RMS)	Best	RMS value type
Ammeter	Moving-iron type	${\longleftarrow}$	Suitable	
	Rectifier type		Unsuitable	Average value type
	Tester		Unsuitable	
	Digital tester		Unsuitable	
Wattmeter	Ammeter / wattmeter type		Suitable	

Safety Considerations

- For safe operation, before using the product, read the instruction manual or user manual that comes with the product carefully or consult your dealer from which you purchased the product or our sales office.
- For safe operation, wiring should be conducted only by qualified engineers who have sufficient technical knowledge about electrical work or wiring.
- Customers, who want to use the products introduced in this catalog for special systems or devices such as for atomic-energy control, aerospace use, medical use, passenger vehicle, and traffic control, are requested to consult with our sales office.
- Customers are requested to prepare safety measures when they apply the products introduced in this catalog to such systems or facilities that will affect human lives or cause severe damage to property if the products become faulty.

Before purchasing this product

- Please note that for product improvement, the appearance and specifications may be subject to change without prior notice.
- Please note in advance that printed and actual colors may differ slightly.
- For the details of the products included in this catalog, contact your dealer or our sales office.

F- Fuji Electric Co., Ltd.

Gate City Ohsaki, East Tower, 11-2, Osaki 1-chome, Shinagawa-ku, Tokyo 141-0032, Japan Phone : (03)5435-7111